

Track Fitting with the new Event Model

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LHCb Joint OT/IT Software Meeting, NIKHEF, 5th September 2005

- *Preliminary work: status of new Track Event Model*
 - *tests / validation of classes and tools of the new TEM*
 - *status of the new TEM*
- *Track fitting status:*
 - *set-up for the tests*
 - *tests / validation of the Kalman track fitting code*
 - *status of the new track fitting code*

Preliminary work: Status of new TEM

In what follows:

- All initial tracks produced with the ideal pattern recognition of the old TEM
- Tracks not fitted
- True states at each measurement (z-)position
- Tracks selection: loose quality cuts:
 - *Only long tracks*
 - *Momentum > 1 GeV*
 - *#of hits on track > 20*

OLD

nothing extra done

NEW

- TrFitTracks converted to Tracks

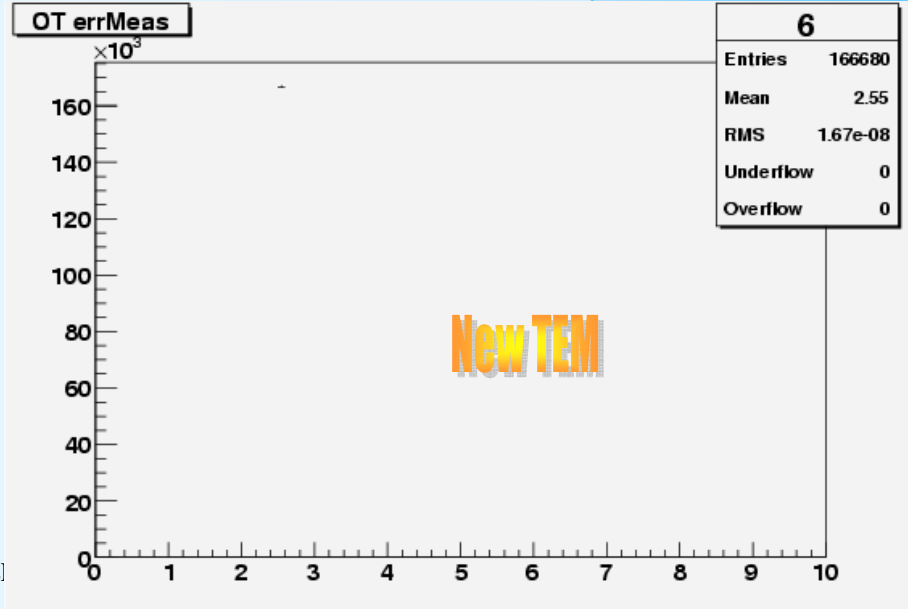
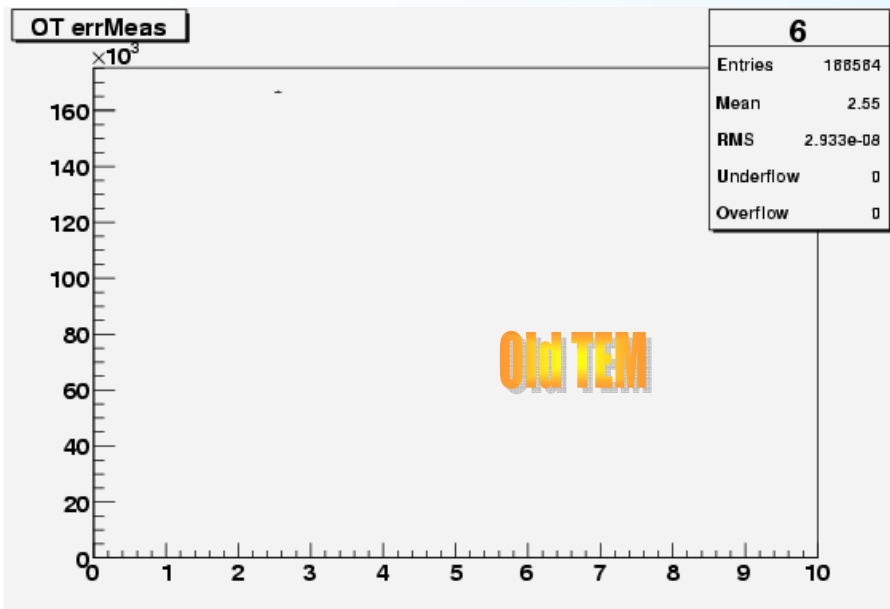
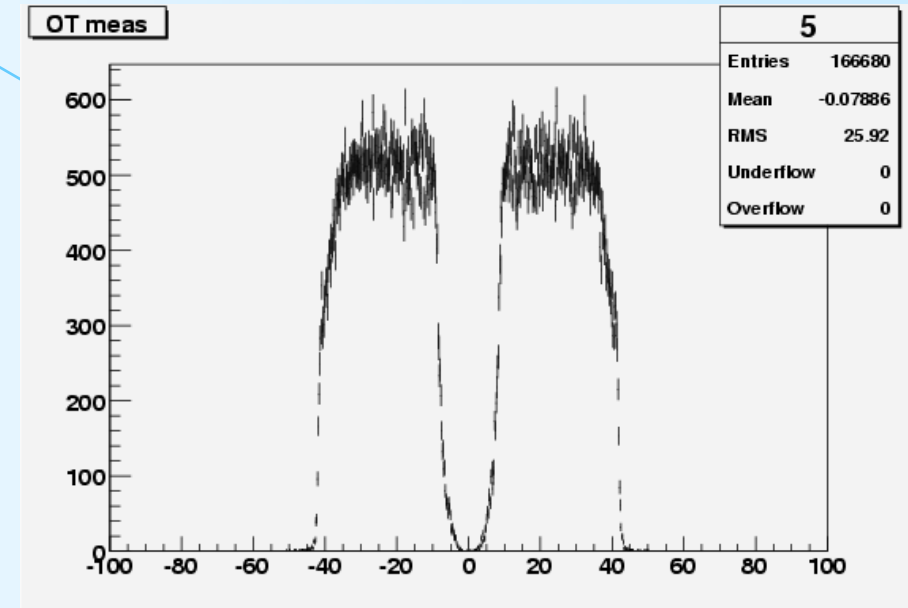
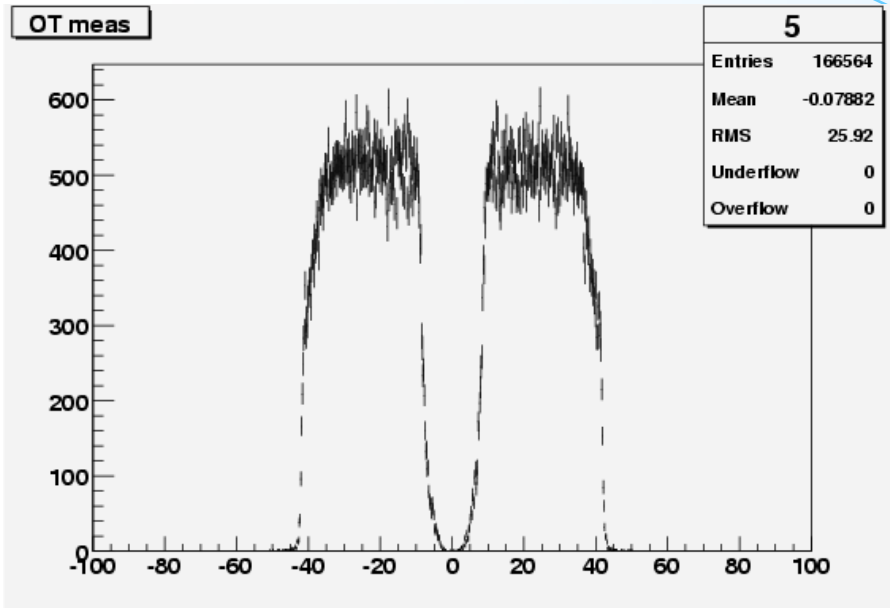
→ have LHCbIDs and measurements

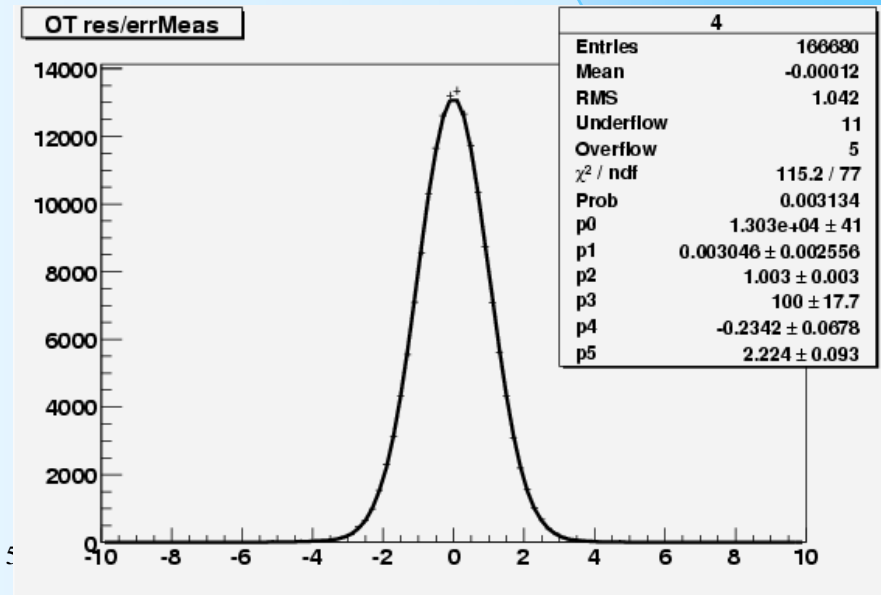
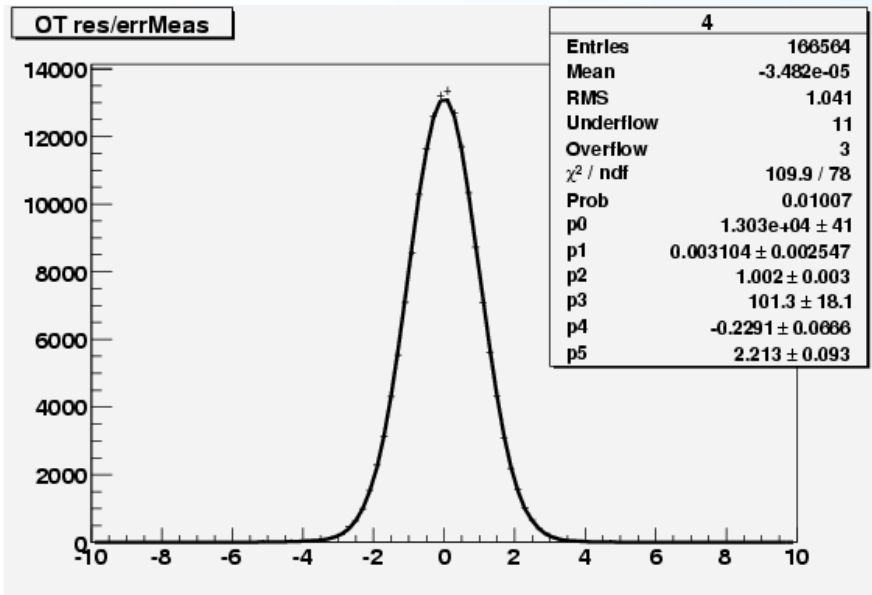
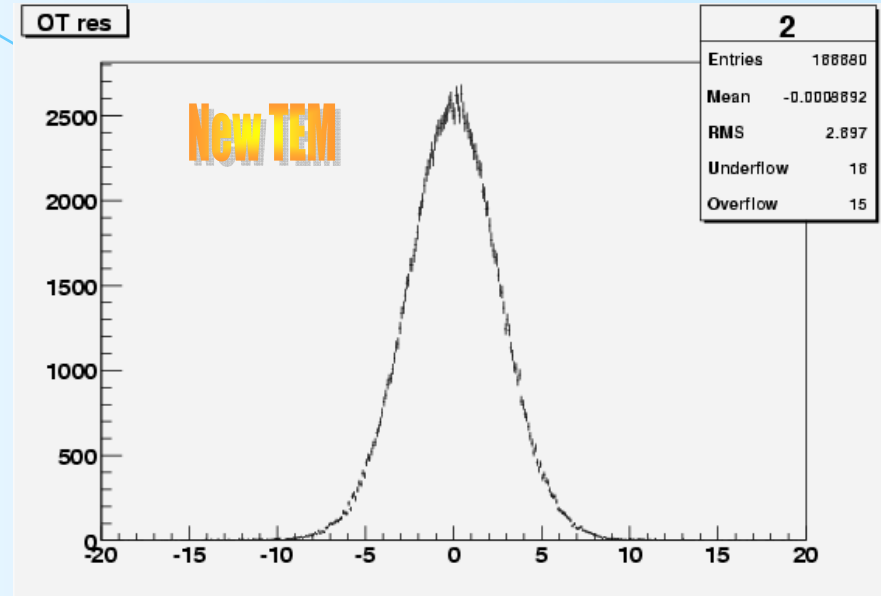
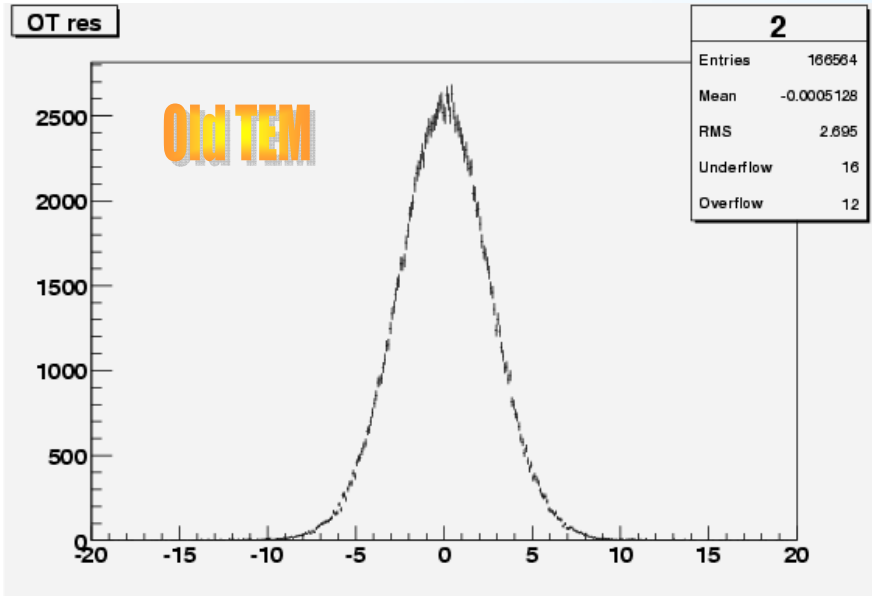
Disclaimer:

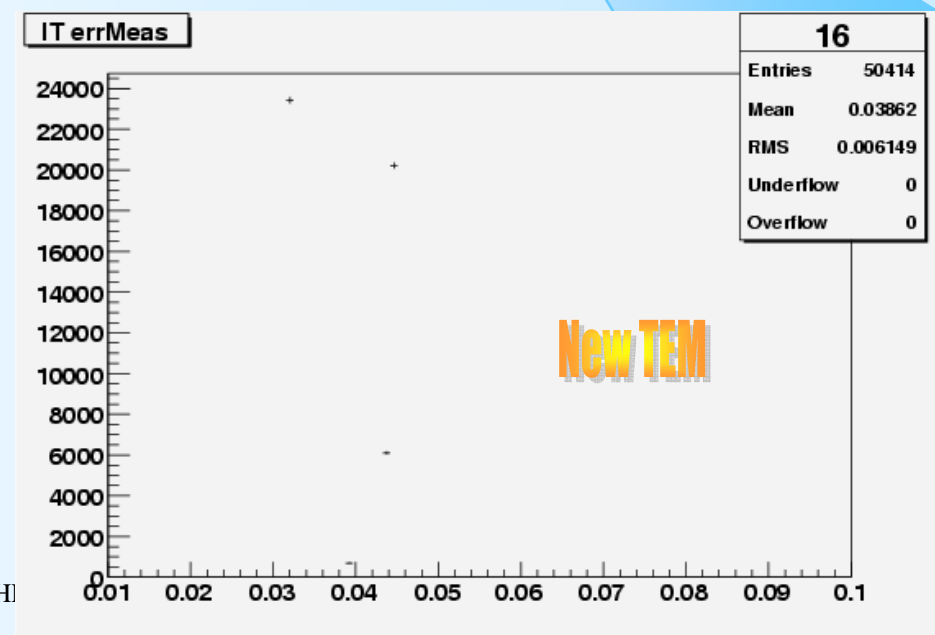
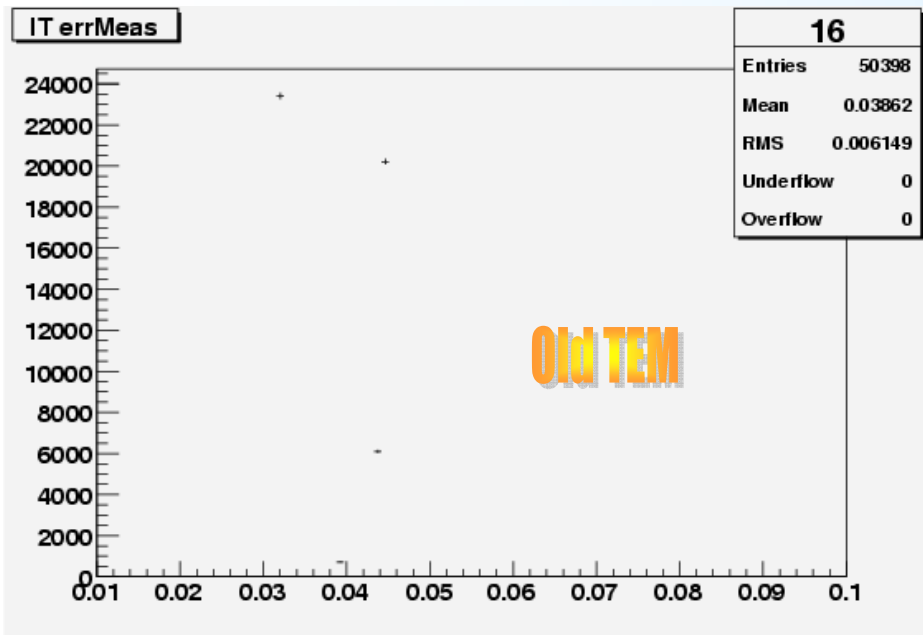
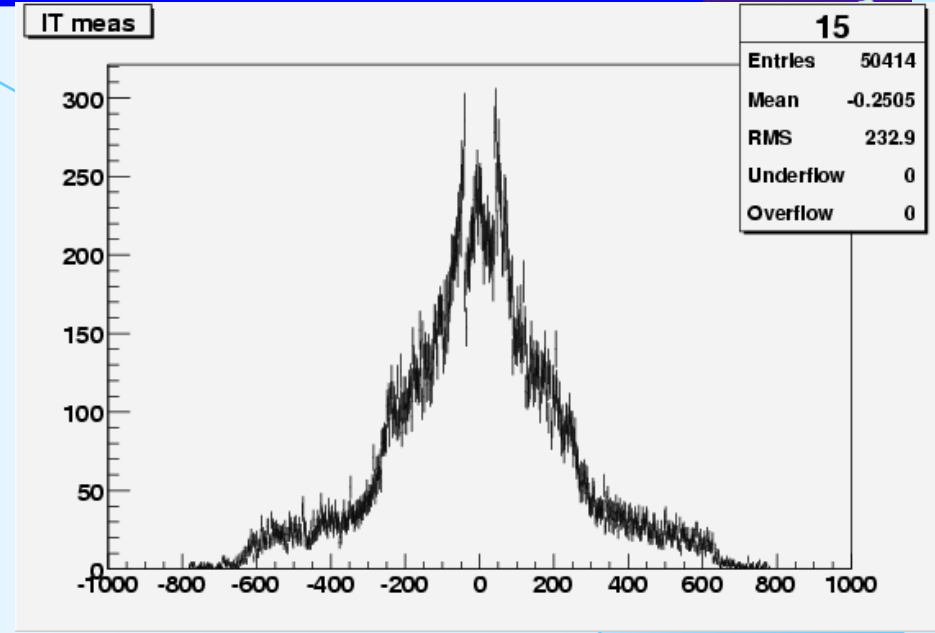
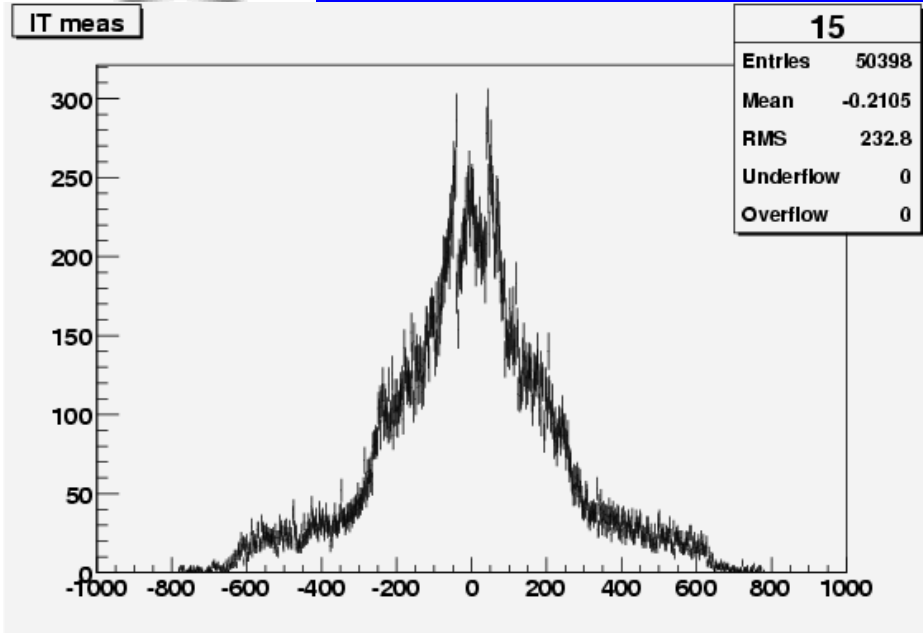
- No attempt here to understand some features found already in the old TEM!
 - *Interesting in its own right but not purpose of these studies*
- Our goal is to test and validate the new code with respect to the old one

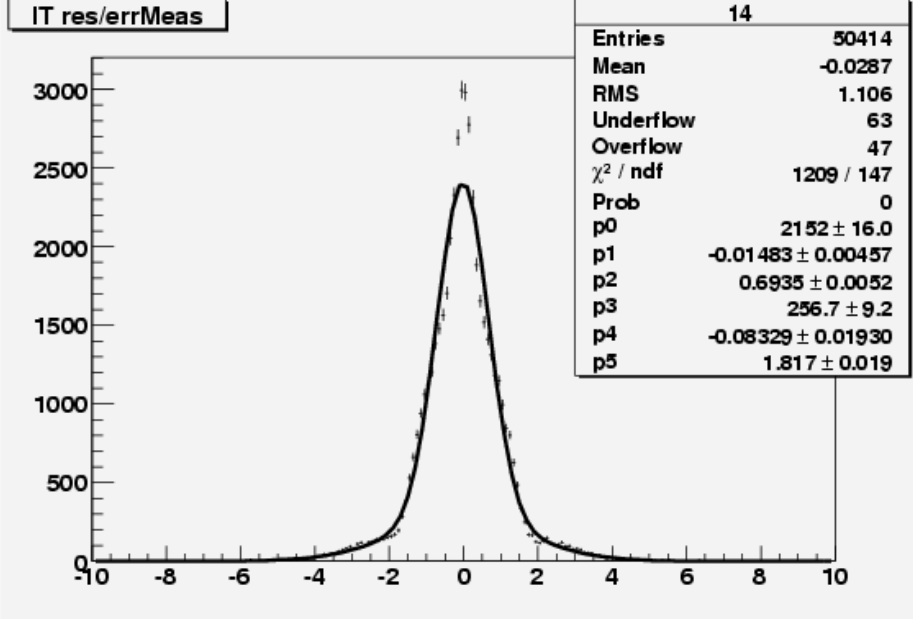
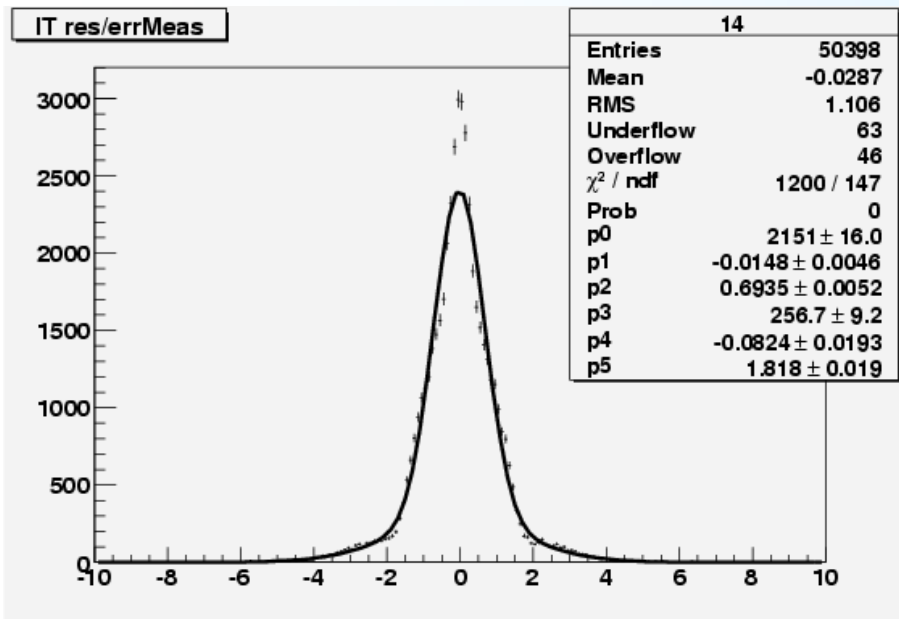
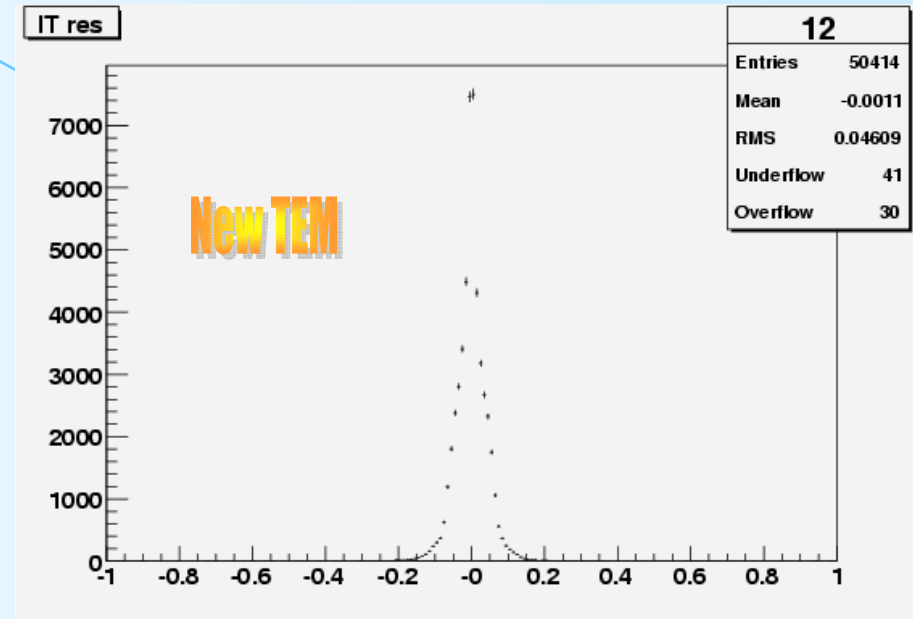
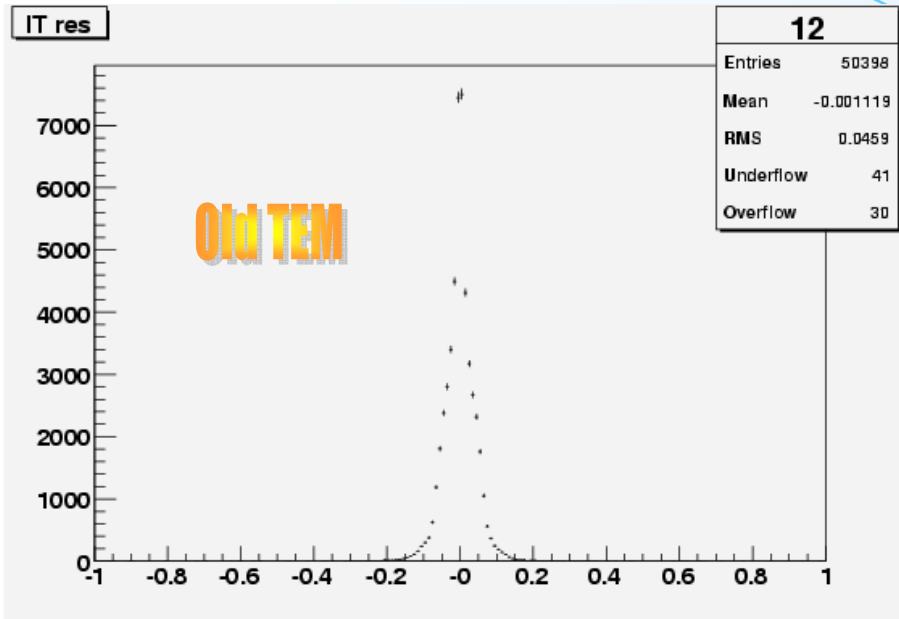
Plots:

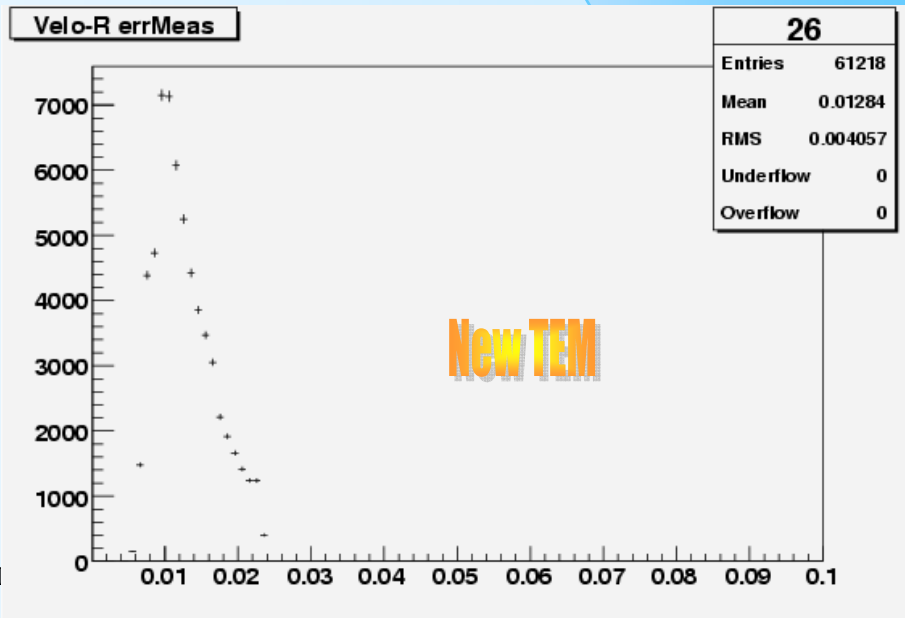
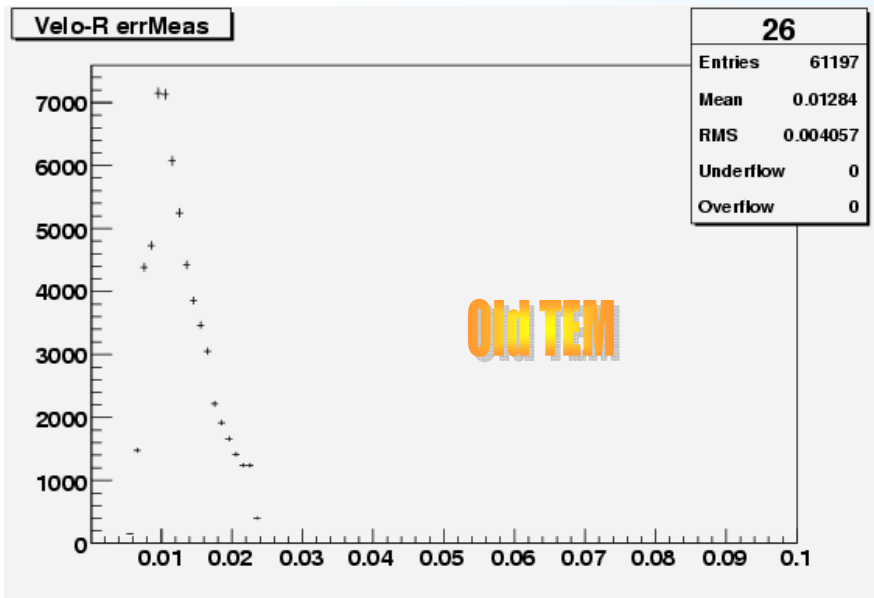
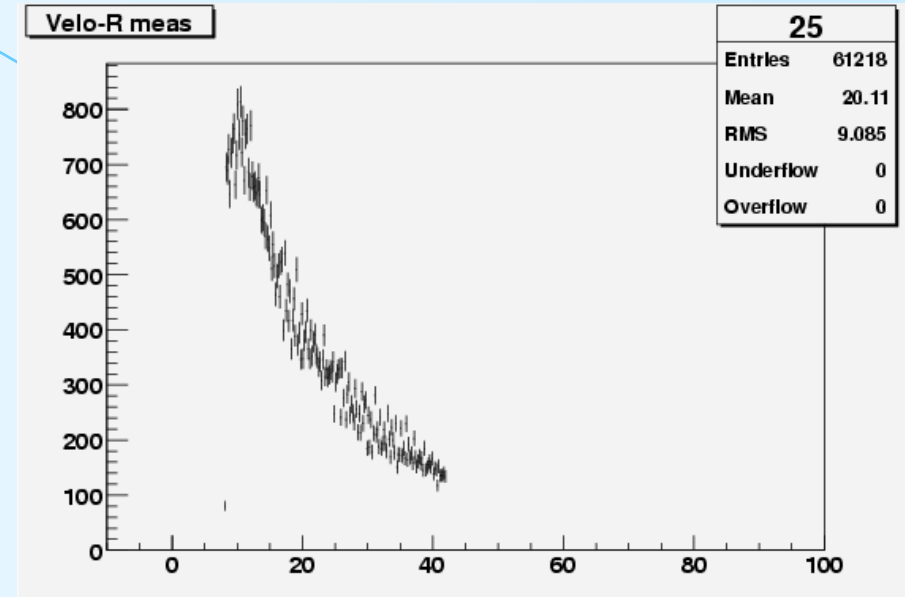
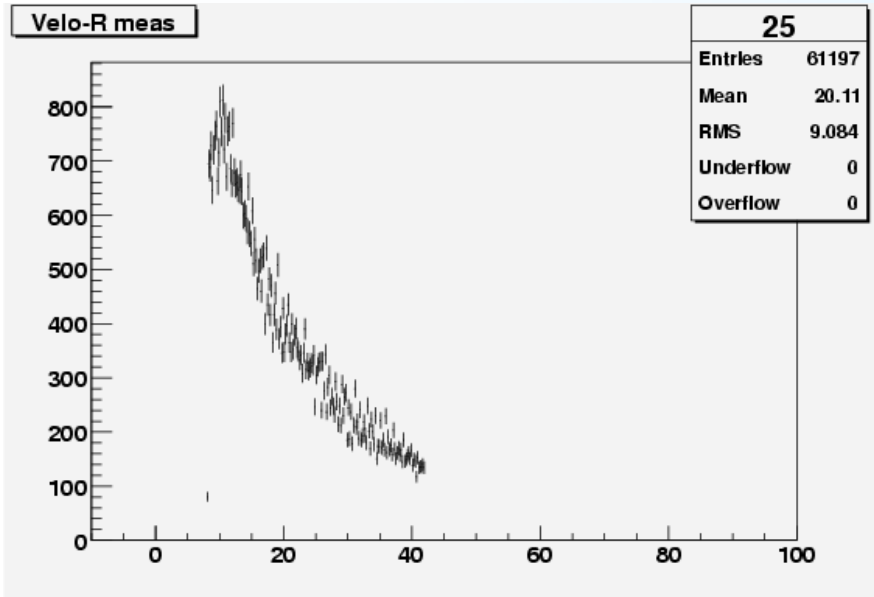
- Separate for OT, IT, Velo-R and Velo- Φ measurements
- \Rightarrow plots produced looping over all pairs of (state,measurement), all at same z-positions, by construction**

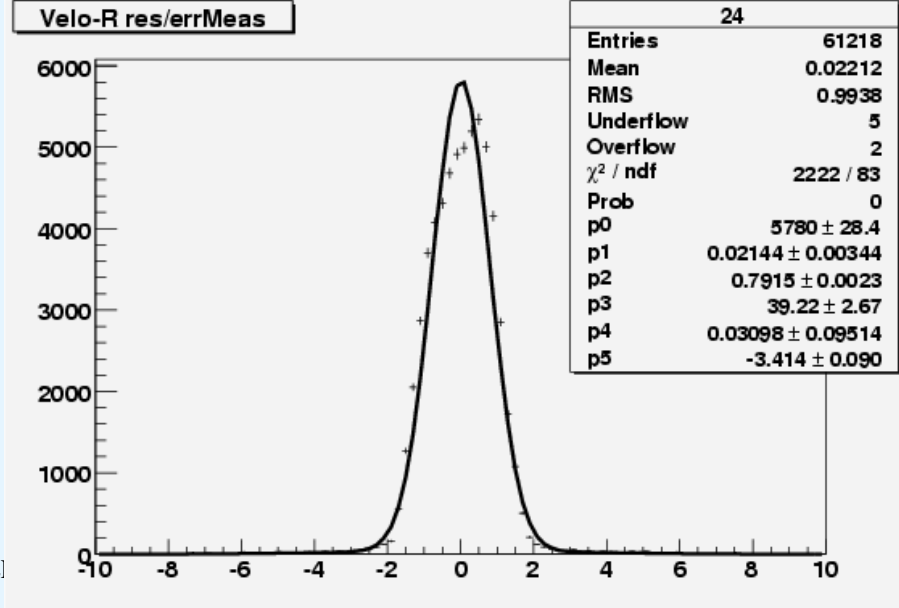
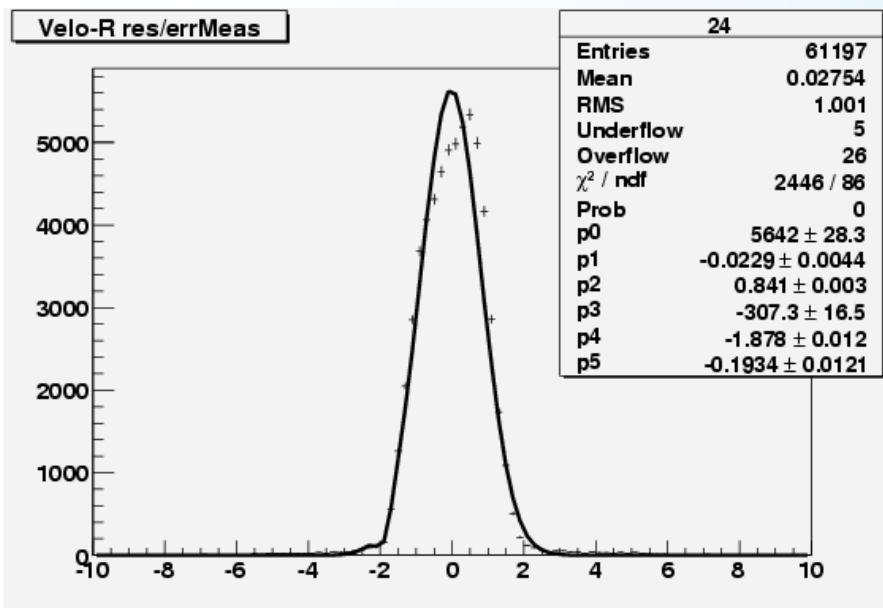
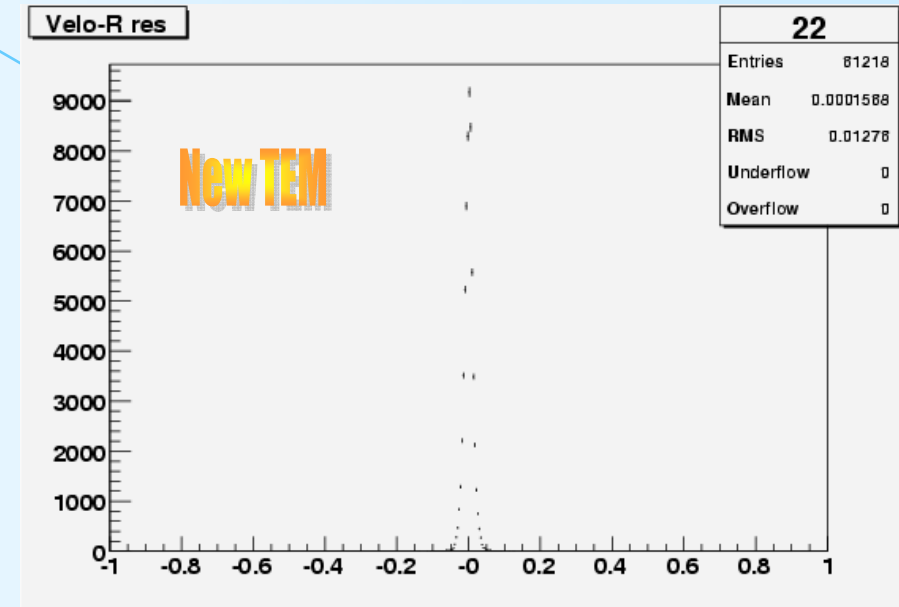
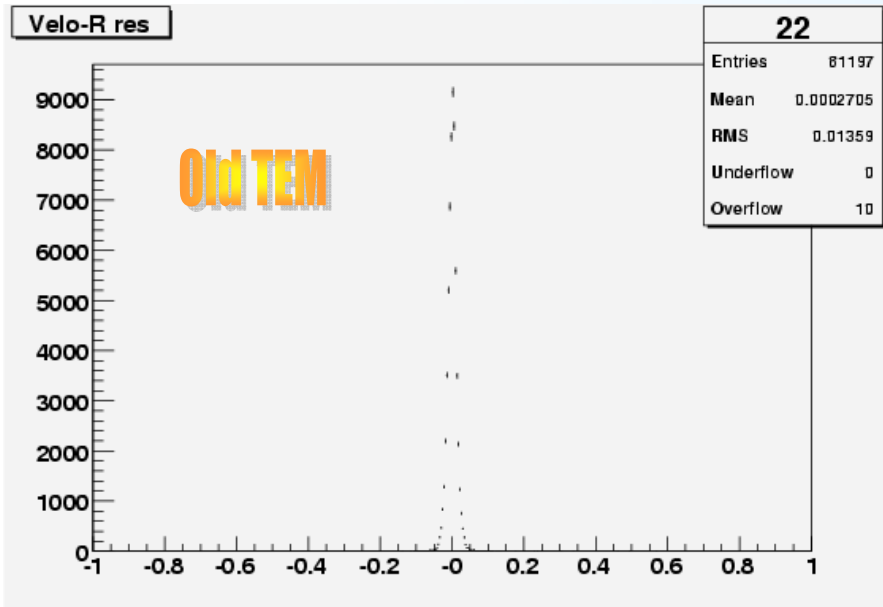


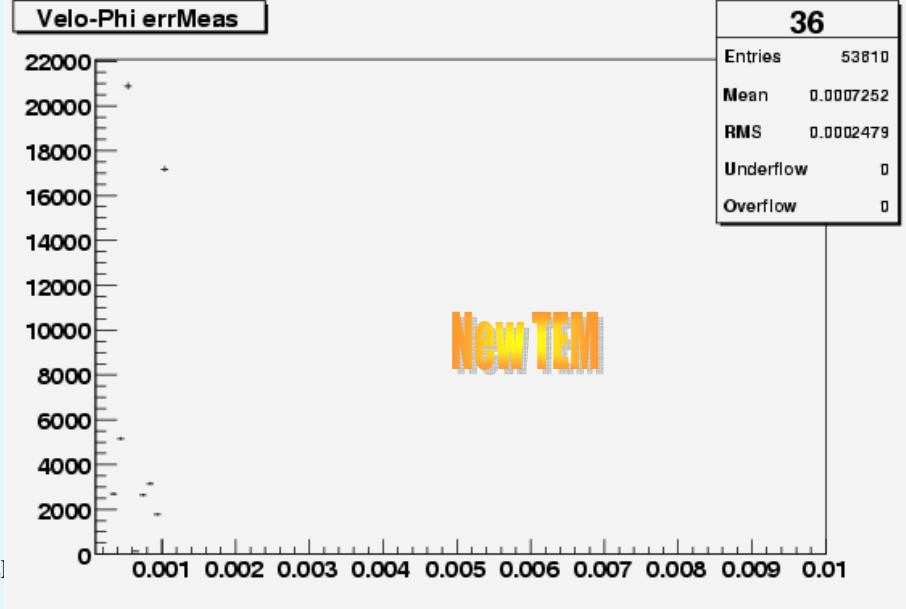
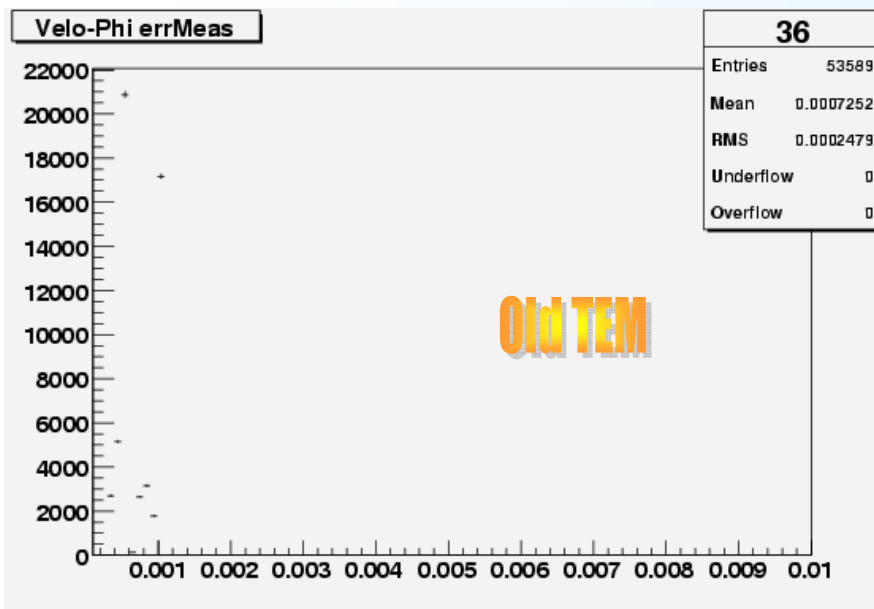
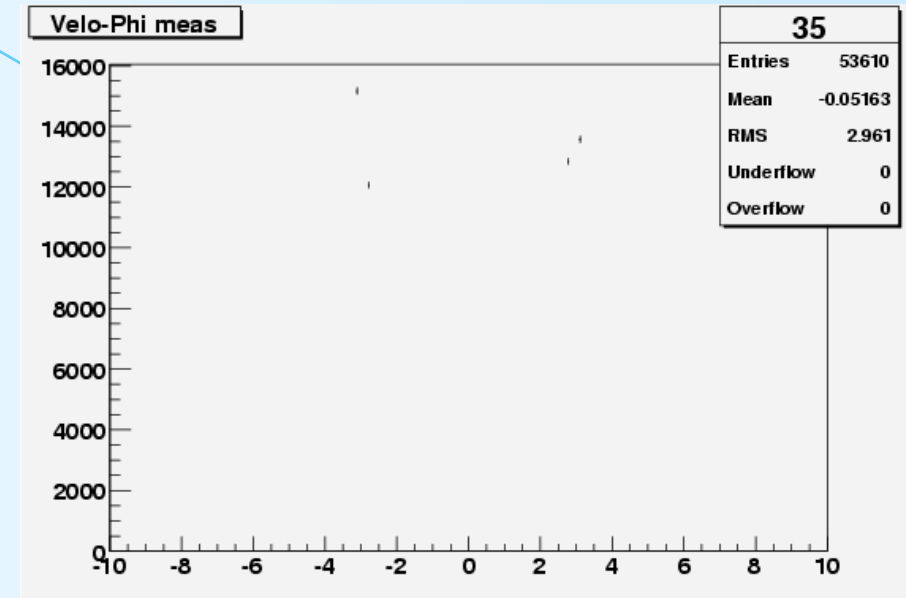
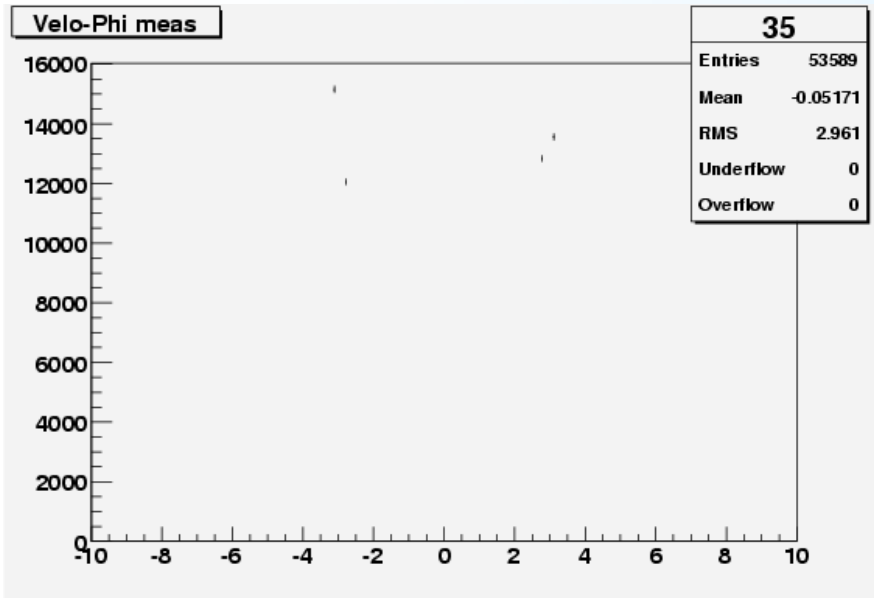


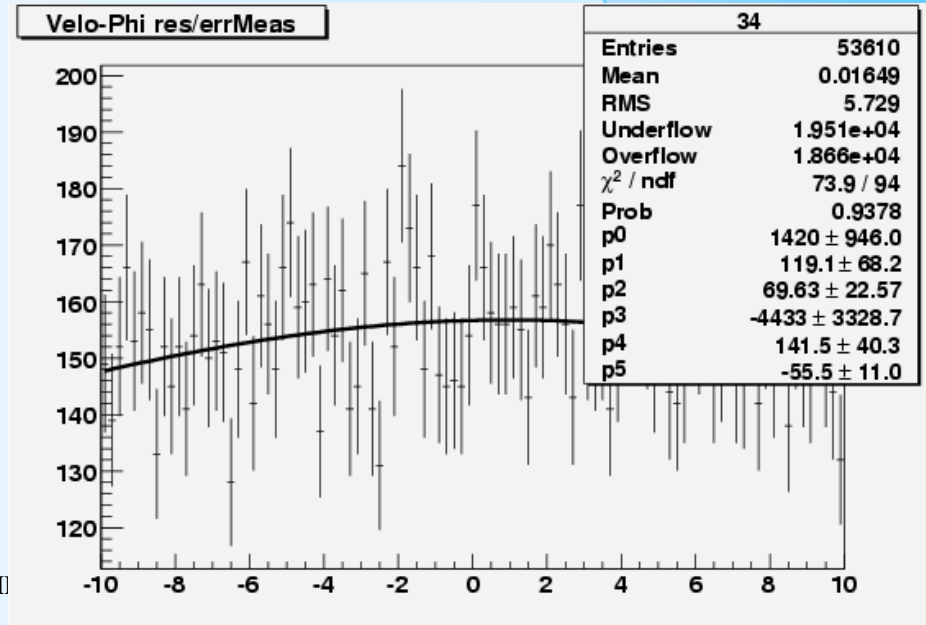
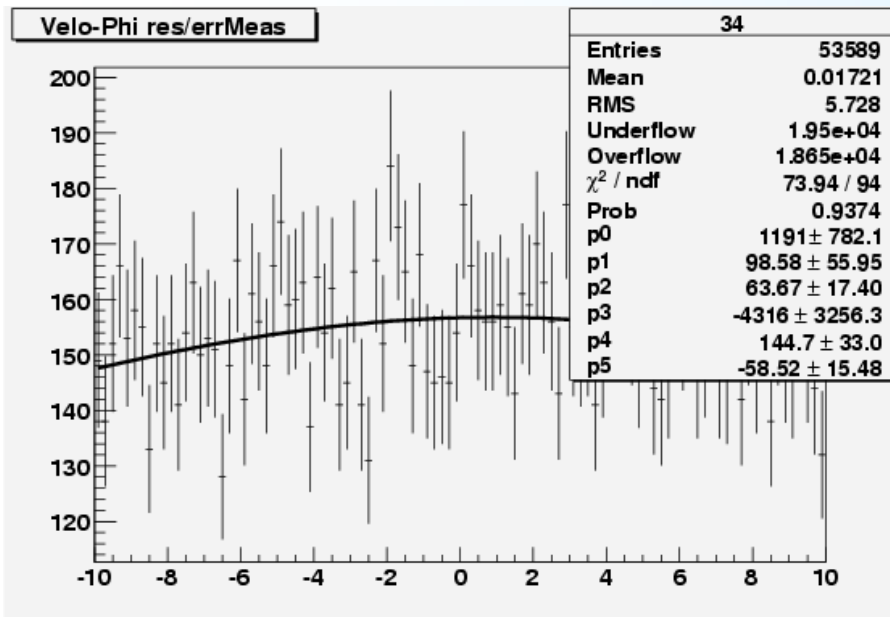
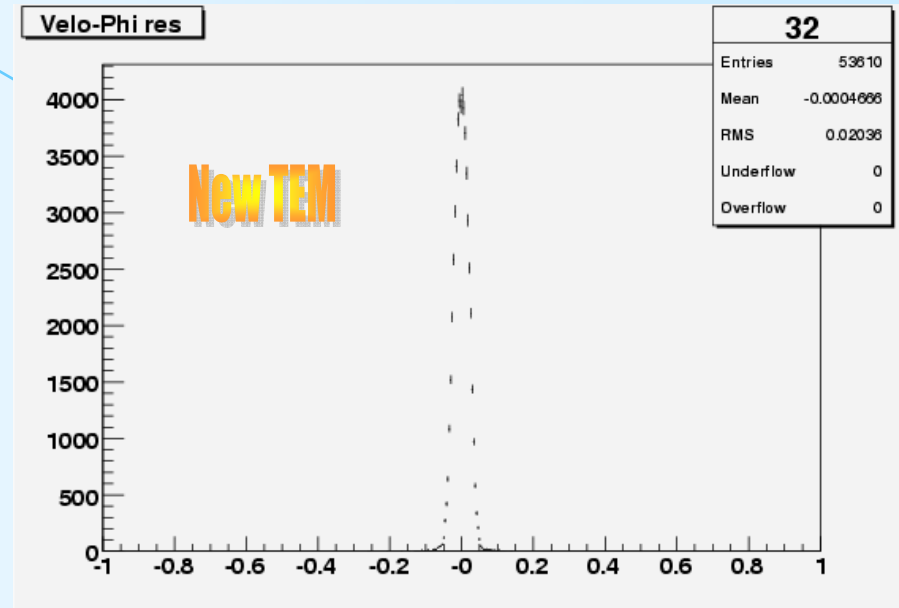
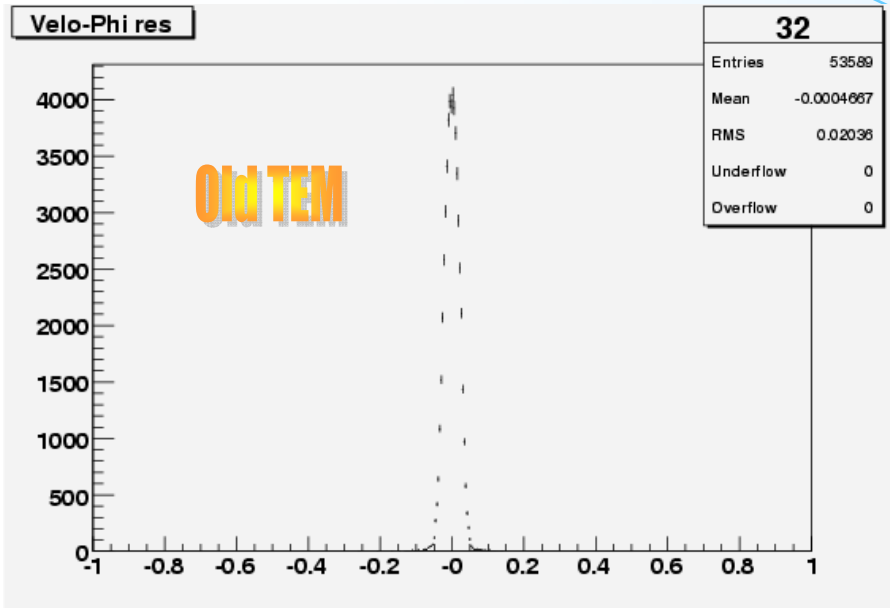












Conclusions of these tests:

- **New TEM classes correctly store the information**
- **The converters are validated**
- **All projectors do the job well**

⇒ **Now we have everything we need to test (with confidence on the input)
the new Kalman filter package Tr/TrackFitter !**

Track Fitting with new TEM: Status

In what follows:

- All initial tracks produced with the ideal pattern recognition of the old TEM
- Tracks selection: loose quality cuts:
 - *Only long tracks*
 - *Momentum > 1 GeV*
 - *#of hits on track > 20*

OLD

- TrFitTracks fitted downstream with old KF code
- states predicted at each meas. position
- TrFitTracks converted to Tracks

NEW

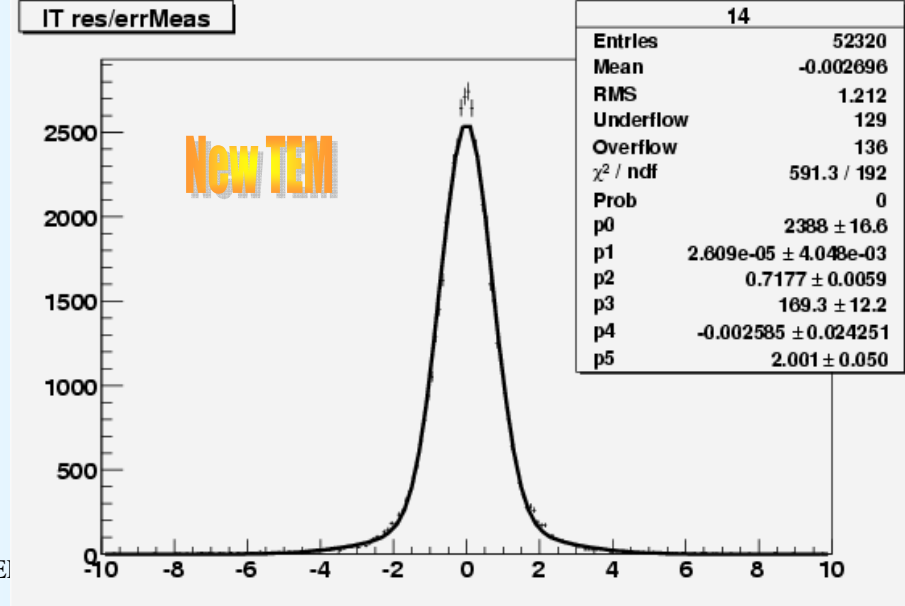
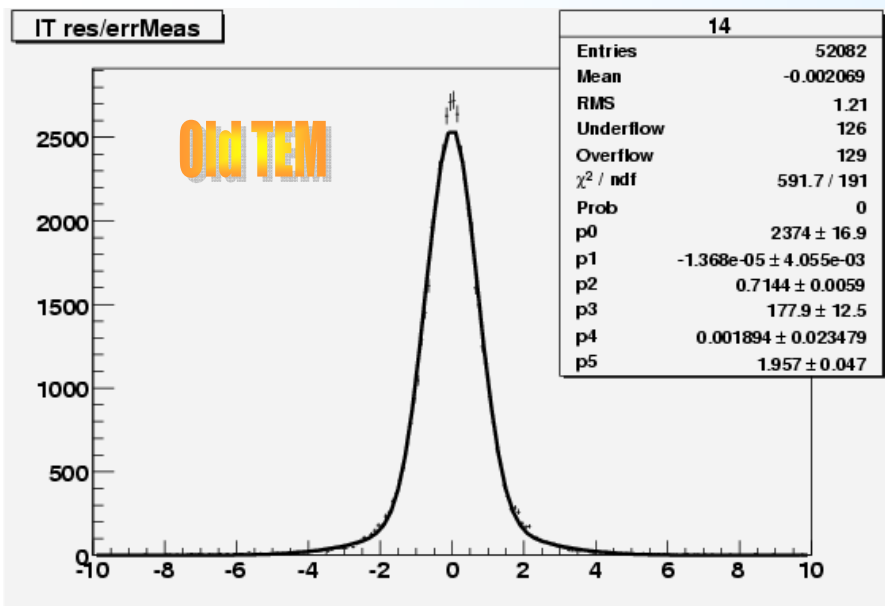
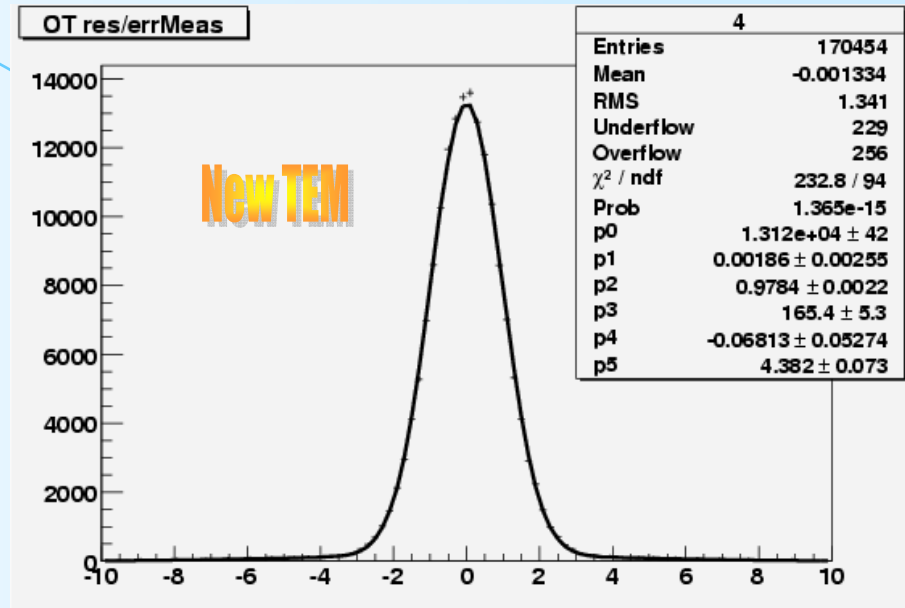
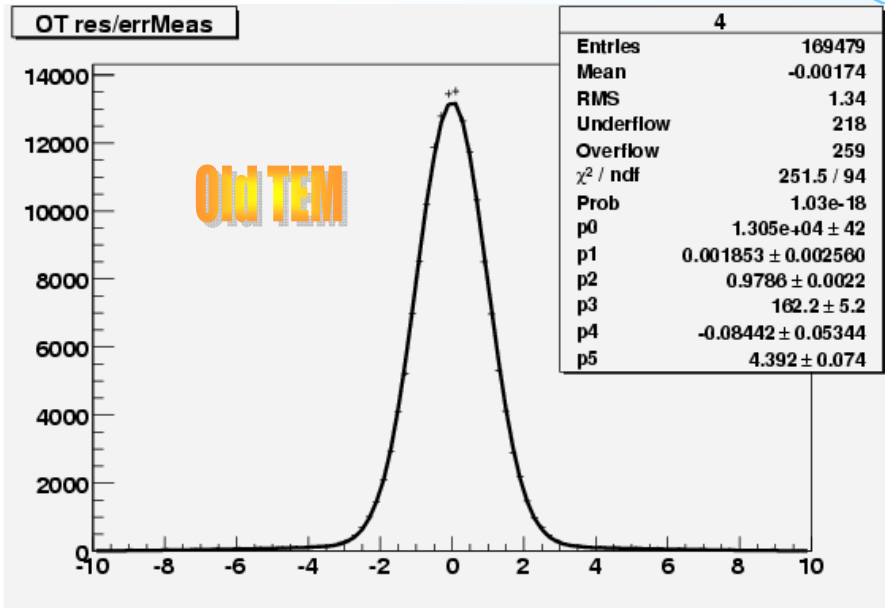
- non-fitted TrFitTracks converted to Tracks
- Tracks fitted downstream with new TEM KF package
- States predicted at each meas. position

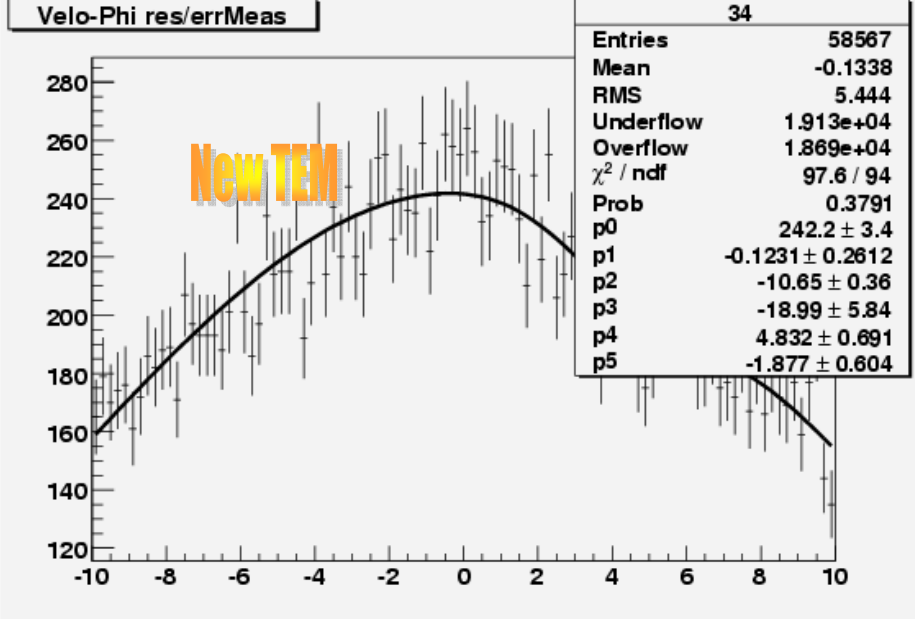
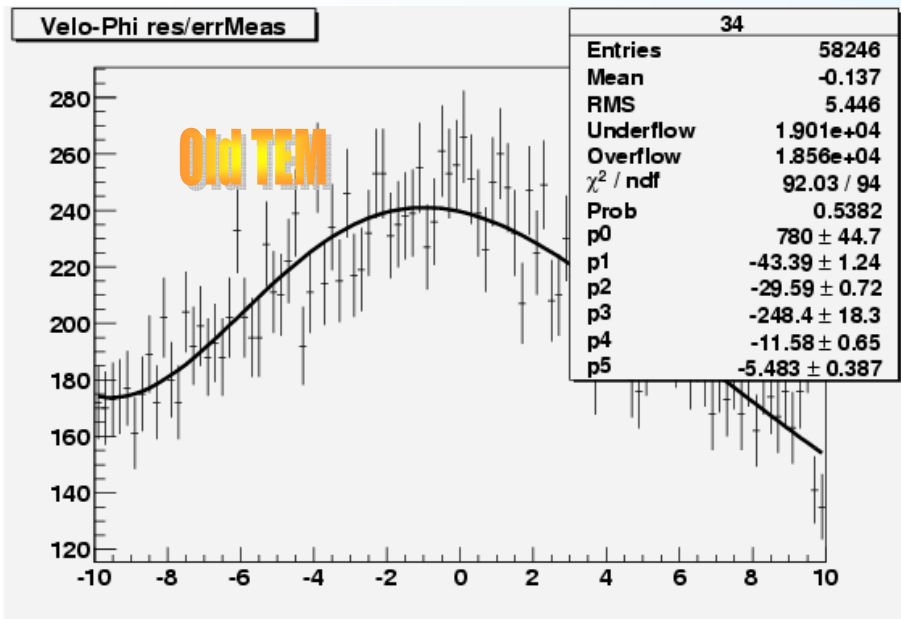
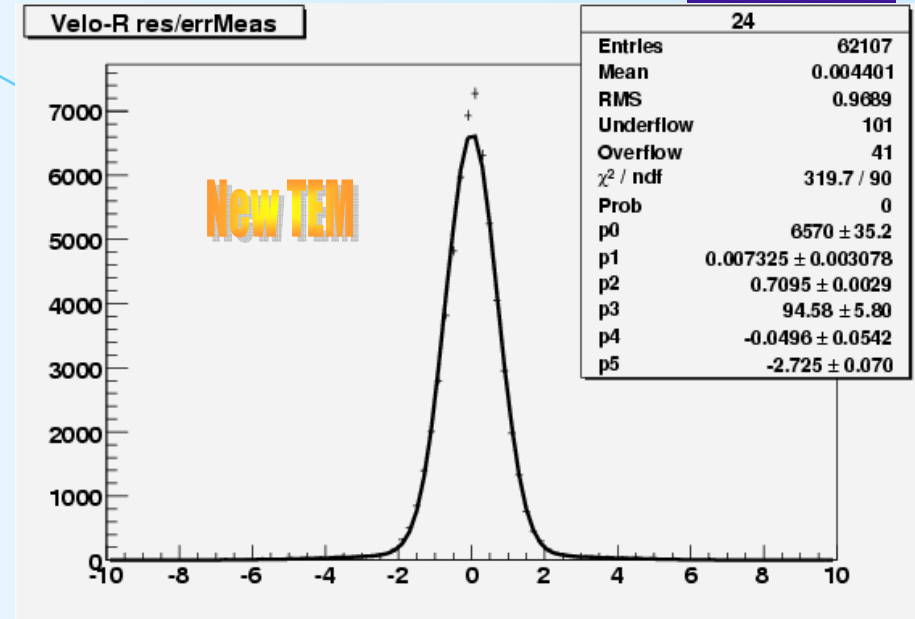
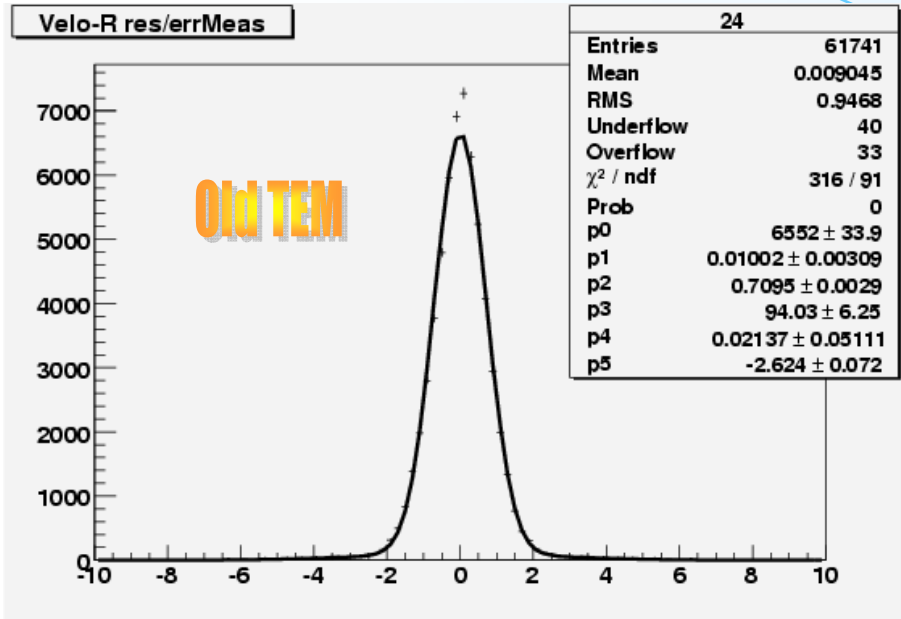
Plots:

- Separate for OT, IT, Velo-R and Velo- Φ measurements

⇒ plots produced looping over all pairs of (state,measurement),

all at same z-positions, by construction





Conclusions of these tests:

- The new TEM Kalman Filter package is now working!

Remarks :

- New KF package does not yet implement all the functionality of the old code
 - *Only downstream fitting implemented*
 - *No outliers removal implemented*
 - *Not yet possible to iterate filtering-smoothing sequence*
- **Timing not yet compared:**
“first get a working version, then worry about timing”
- Tests will continue until everything is understood ...

**Final conclusion:
Back on Track !**