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## <u>Status of new tracking data model</u> <u>"End-user" Classes</u>

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## In short ...

### Driving idea:

- > agree on the interfaces
- > move the code adiabatically in steps
  - code always working, smooth implementation of the interfaces

## Visible to the user:

- tracks & states
- > propagators

## To help the tracking/pattern recognition developers:

- > nodes & measurements
- projectors

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#### Details on status of implementation: http://cern.ch/eduardo.rodrigues/lhcb/tracking/event\_model/index.html

(note: place of evolving ideas/implementations ... )



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# <u>Working plan</u>

1. <u>Reach agreement on TrTrack, TrState, extrapolators interface</u>

M3 M4 M5



GOAL: standard output of all fitting algorithms, online & offline

- > client interface: how to use the tracks, ...
- > minimal interference with present code
  - $\Rightarrow$  e.g. leave measurements untouched at this stage

## □ STEPS: 1a) reach final agreement on this set of classes (today?)

1b) implementation of converters

### TrFitTrackToTrTrackCnv & TrgTrackToTrTrackCnv

- → needed to make sure the TrTracks work !
  - 2a) make TrFitTrack & TrgTrack inherit from TrTrack
- > at this point we could already imagine some full MC production with new model !

## □ TIMESCALE: 1a) end of the week

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1b) 1 week after agreement (implementation + test)

### 2a) 2 weeks



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# <u>Working plan</u>

2. <u>Reach agreement on TrMeasurement, TrNode, projectors interface</u>

M3 M4 M5

- GOAL: have some common base classes for
  - pattern recognition and fitting algorithms
  - > re-use as much as possible the existing code and packages
  - Tr(g)Event minimally/not touched
  - > end-user/client code is unchanged !

□ STEPS: 1a) get some first agreement on proposed structure

- > projectors as Gaudi tools, need for TrMeasurement & TrNode classes
  - 1b) re-build all necessary info from persistency
  - 2a) XxxClusterOnTrack replaced by TrNode,
    - XxxCluster derived from TrMeasurement
  - 2b) pattern recognition and fitting algorithms make full use of
    - projectors and new measurement classes



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# <u> TrTracks (1/2)</u>

M3 M4 M5

### Data members

- > m\_type: OK. Related enums are no problem to persistency
  - → variation: make use of bitfields
- > m\_historyFlag: OK. Enum.
  - → variation: change the name?
- > m\_errorFlag: renamed to m\_flag . Uses bitfields with contents = { valid, ... }
- > m\_chi2: becomes m\_chi2PerDoF
  - → more commonly used

#### m\_nDoF: keep it?

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- -> pros: fast access to info
- → variation: remove it
  - -> pros: saves space, but needs some calculations to get it back

#### > m\_closestState: state closest to beam-line, to be persistent

- → more commonly used
- → variation: call it m\_firstState
- > m\_states: proposal to have a SmartRefVector
  - → persistency on demand: subset of states to be persistified (Beam-line, TT, T)
  - → variation: use a std::map with location as key (e.g. AtTT)



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## <u> TrTracks (2/2)</u>

## Public methods

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- > end-user methods for fast/easy access to general track information
  - e.g StatusCode positionAndMomentum (double z, ITrExtrapolator \*extrapolator,
    - ParticleID &pid, HepPoint3D &pos, HepVector3D &mom, HepSymMatrix &cov6D)

M3 M4 M5

- > methods to get direct access to closest state, by z-pos or plane
  - → commonly used methods in tracking code
    - -> pros: friendly and simple interface
- > methods with extrapolator interface as argument:
  - -> pros: hide repeated operations
    - (e.g. aTrack->closestState()->extrapolate())
    - → variation: move these methods to the extrapolator interface
- > virtual methods: # brought to a minimum
  - closestState(z/HepPlane3D), reset(), clone(), producedByAlgo()



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#### Data members

- > m\_type: enum {StraightLine, HasMomentum} Fine
- > m\_location: enum key for state locations (e.g. AtTT, BegRICH1, ...)

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> other data members: z-position, state vector, covariance

#### **Public methods**

- > # of "setter" methods minimized
- > methods related to position/slopes: implemented
  - → no need to be virtual
- > methods with Q/P or momentum: all virtual

### **Derived classes**

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- > 2 strategies to derive from TrState:
  - → TrStateL -> TrState (Q/P and 5 components)
  - → TrStateL, TrStateP -> TrState



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## <u> Tools - extrapolators</u>

## ITrExtrapolator

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## Public methods

- > extrapolators to z and HepPlane3D
  - virtual StatusCode **propagate** (**TrState** \*state, double z, ParticleID partId=ParticleID(211))=0

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- > Issue: need for an extrapolation to some kind of surface
  - → How to define a surface?

Can use fosr the moment a typedef to HepPlane3D in a "Surface" class

> interface ITrExtrapolator defined and essentially agreed ...

## TrLinearExtrapolator

## Public methods

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- > already implemented
- > serves as (simple) example