

# REPARAMATERIZING TRACK ERRORS IN DC06

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**T-Rec Meeting**

**26 May 2008**



**A big thanks to  
Hugo and Jose  
for their help!**

# OVERVIEW

- Motivation
- Fitting procedure
- DC06 results
  - Best fit polynomials & Residuals
  - Impact on HLT selections
- Future work

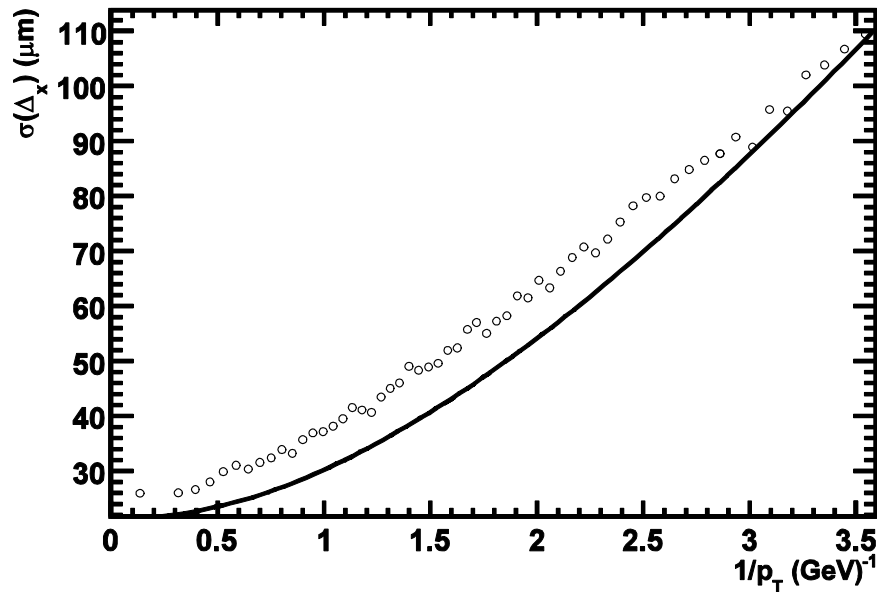
# WHY ARE TRACK ERRORS IMPORTANT?

Without a correct calculation of track errors, using significance cuts in the trigger introduces inefficiencies

No time for a full fit in HLT2

- Must parameterize the track errors

**The DC04 parametrization no longer works in DC06.**



# **FITTING PROCEDURE**

## ERRORS AS A FUNCTION OF PT

- Follow the same procedure as used in Hugo's DC04 note\*
- The track errors are binned as a function of  $1/p_T$
- A polynomial is fitted to these errors, and used in the HLT to calculate entries in the 5x5 track covariance matrix
  - Errors in x and y are assumed uncorrelated

\* Ref: Hugo Ruiz, LHCb 2005-012

## CALCULATING THE ERRORS (DETAILS)

- Extrapolate the track to the same Z point as the primary vertex
- Calculate the X (or Y) deviation of the track from the PV (binned in  $p_T$ )
- In each bin, use an iterative procedure to estimate the core Gaussian width of the X(Y) deviation from the PV
  - Errors on the PV position are considered negligible, hence ignored

## CALCULATING THE ERRORS (MORE DETAILS)

- For each bin, iterate as follows
  1. Compute RMS; reject tracks  $> 8xRMS$  from the mean
  2. Compute RMS; reject tracks  $> 7xRMS$  from the mean
  3. Compute RMS; perform Gaussian fit in  $\pm 1xRMS$  region;  
Reject tracks  $> 6\sigma$  from the mean
  4. Repeat 3, rejecting tracks  $> 5\sigma$  from the mean
  5. Repeat 3, rejecting tracks  $> 4\sigma$  from the mean
  6. Perform a final Gaussian fit in the  $\pm 3xRMS$  region

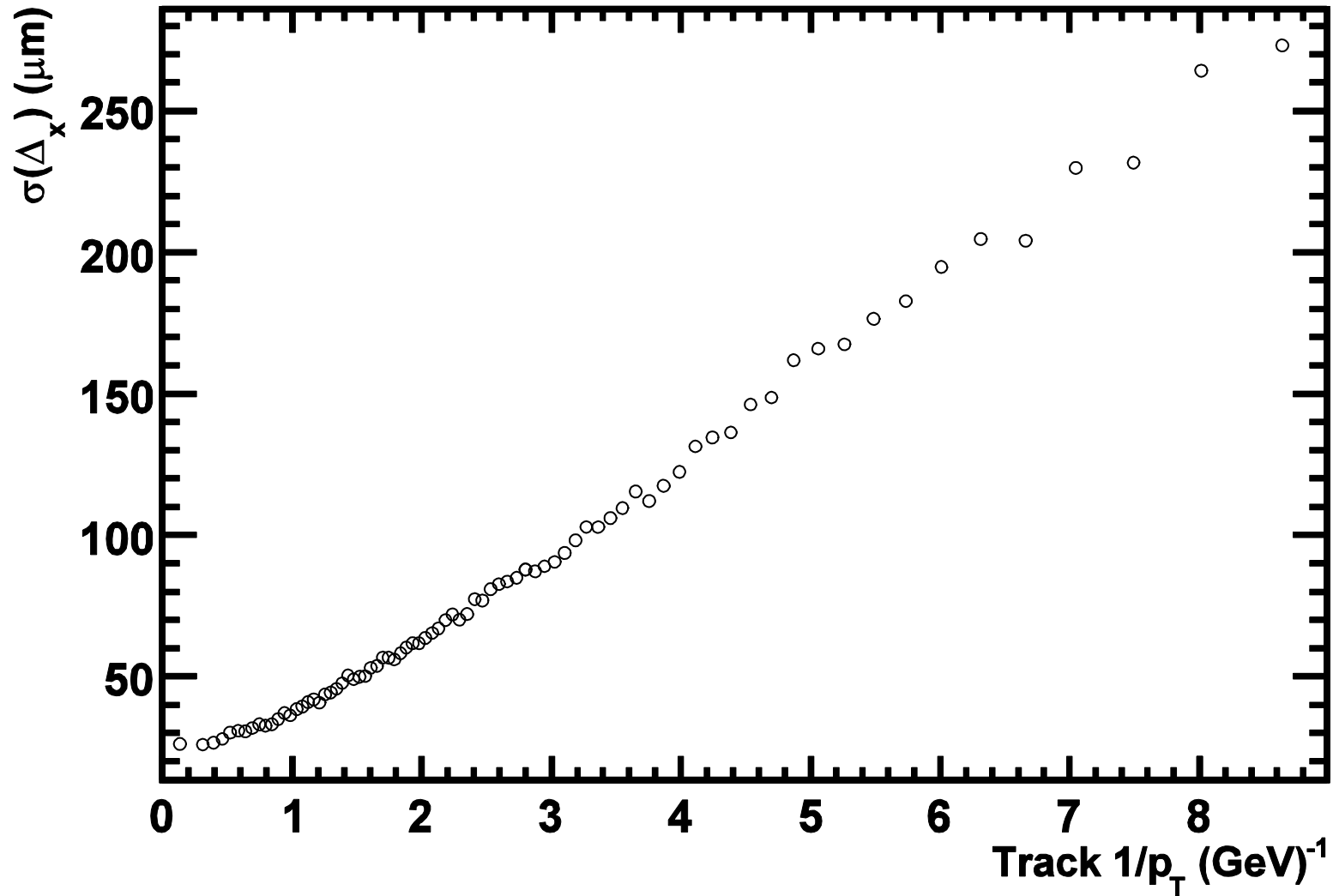
# **DC06 RESULTS**



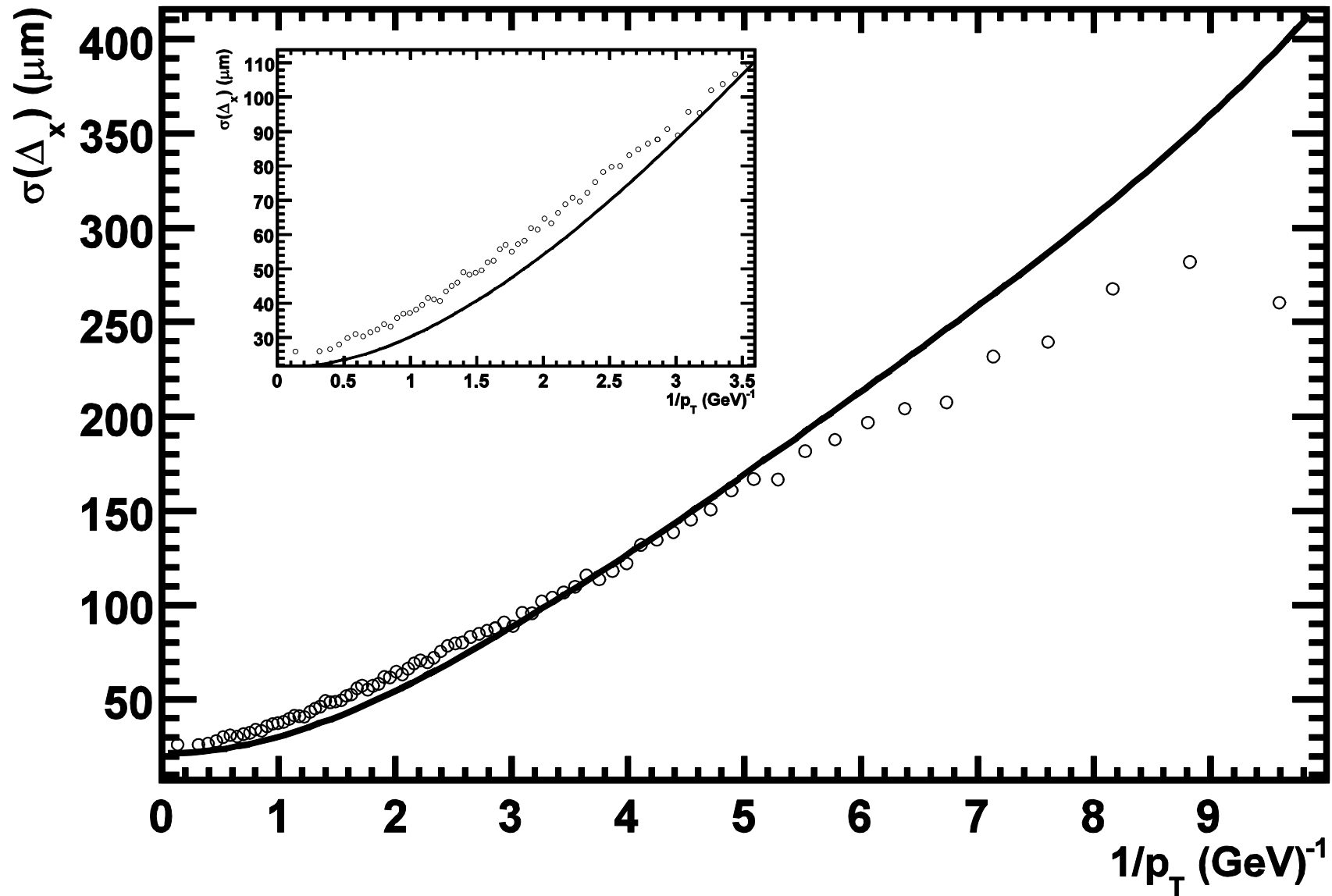
## DATA SAMPLE

- DaVinci v19r12
- 20,000 L0 stripped minbias events
- Select events with 1PV only
- Make all particles as pions using StdNoPIDsPions
  - Only Long tracks used!
- No MC truth information used

# ERRORS AS A FUNCTION OF $1/p_T$



# WITH THE OLD PARAMETRIZATION...

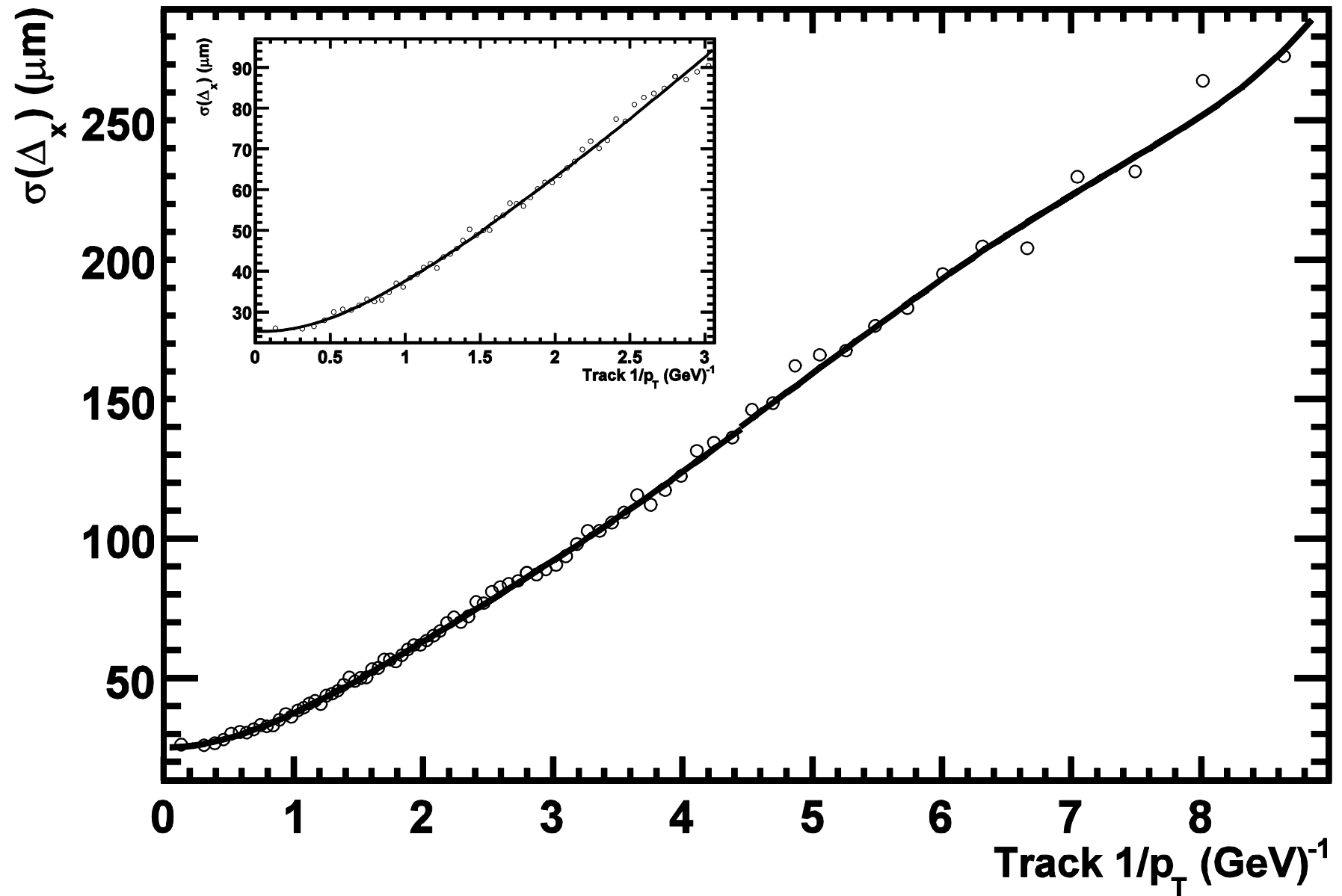


# **BEST FIT POLYNOMIALS**

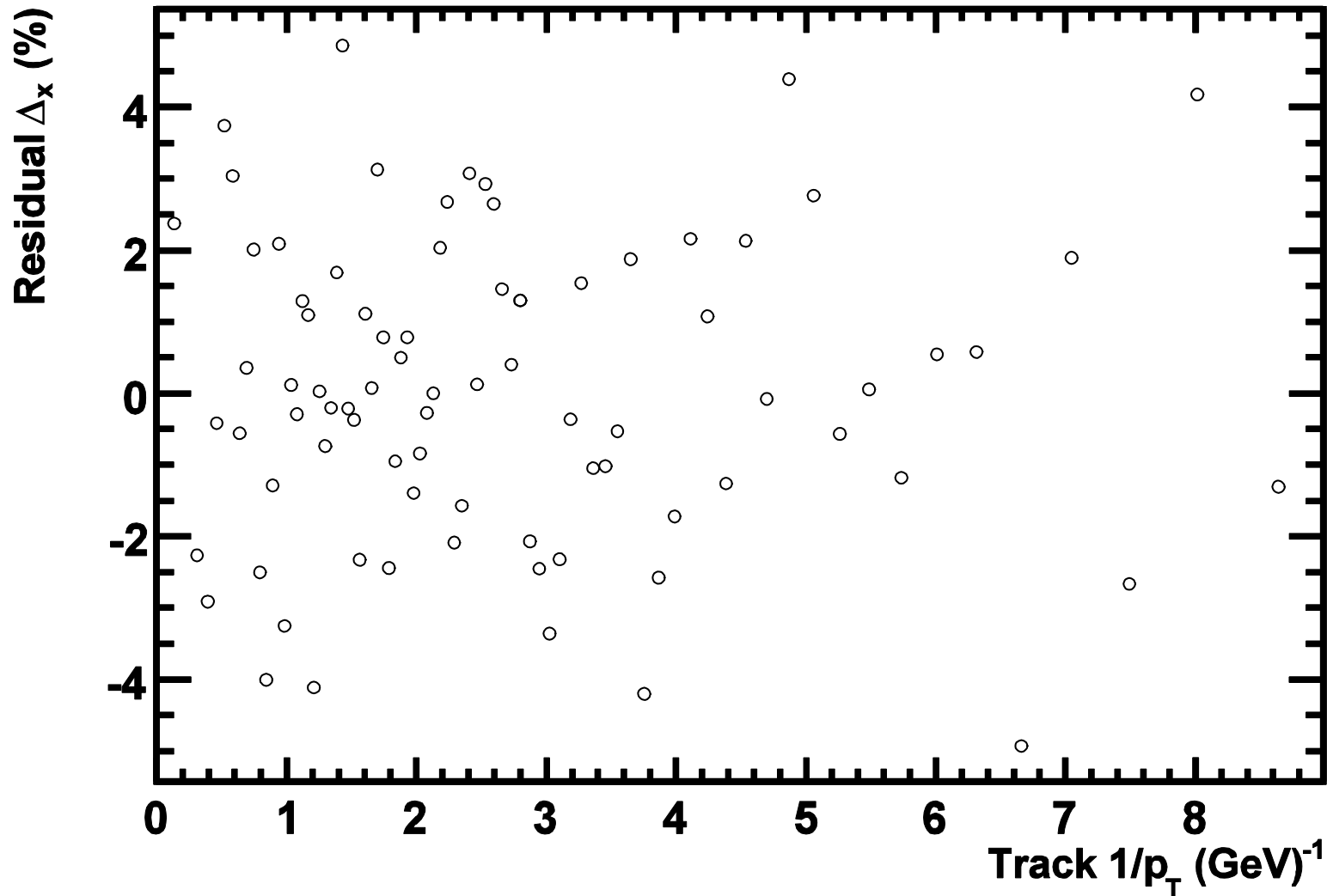
## EXPLANATION

- Plots have been made with second to sixth degree polynomials
- Show the sixth degree fits here, the rest are in the backups
- Note that the first few bins are the most important since they contain the high  $p_T$  signal-like tracks
  - The first bin contains all tracks with  $p_T > 10$  GeV and is hence especially important

# FITTING WITH A 6<sup>TH</sup> DEGREE POLY

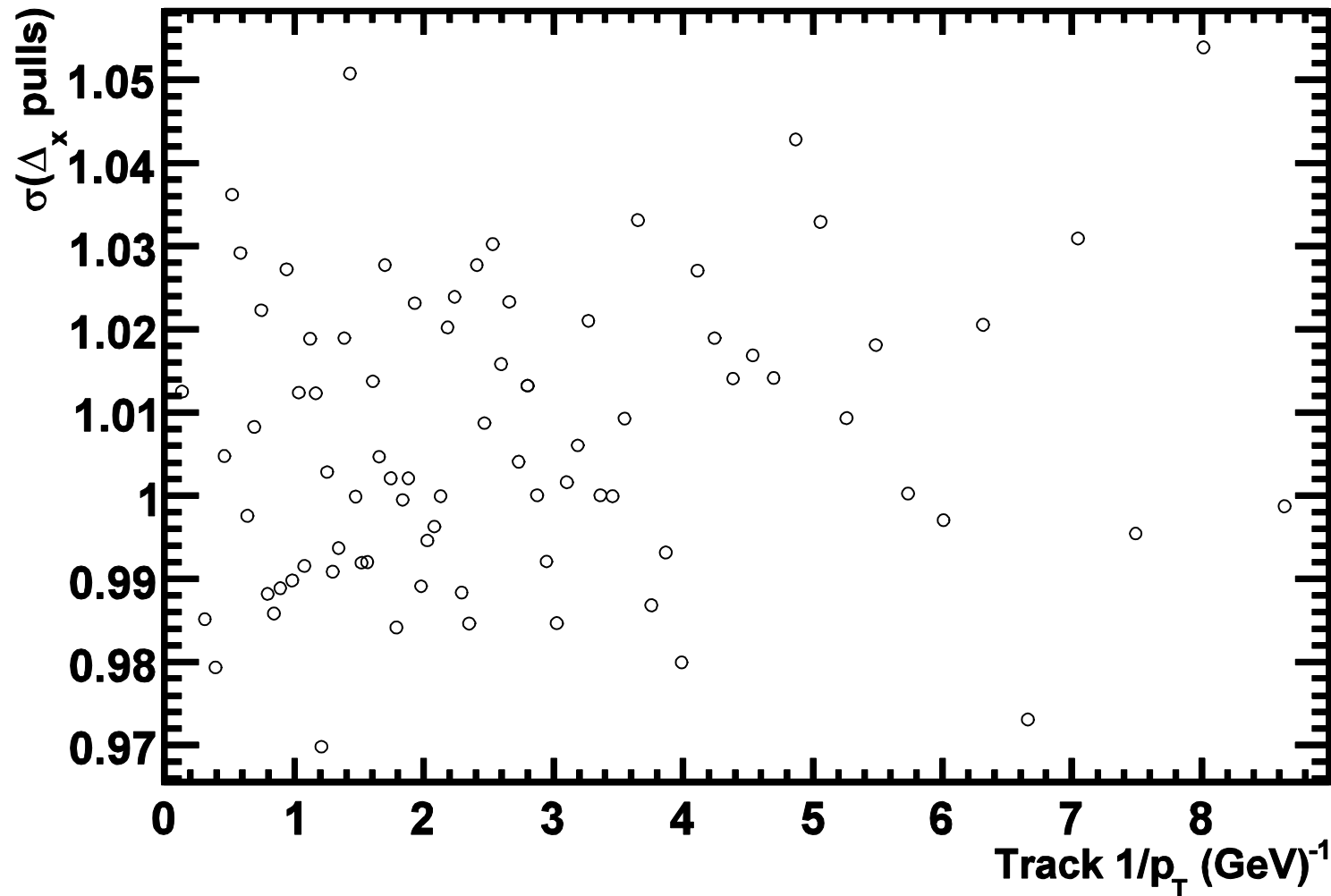


## RESIDUALS WITH A 6<sup>TH</sup> DEG. POLY FIT



This plot shows the residual between the fitted and measured error for each bin of  $p_T$ , calculated at the midpoint of the bin.

## PULLS WITH A 6<sup>TH</sup> DEG. POLY FIT

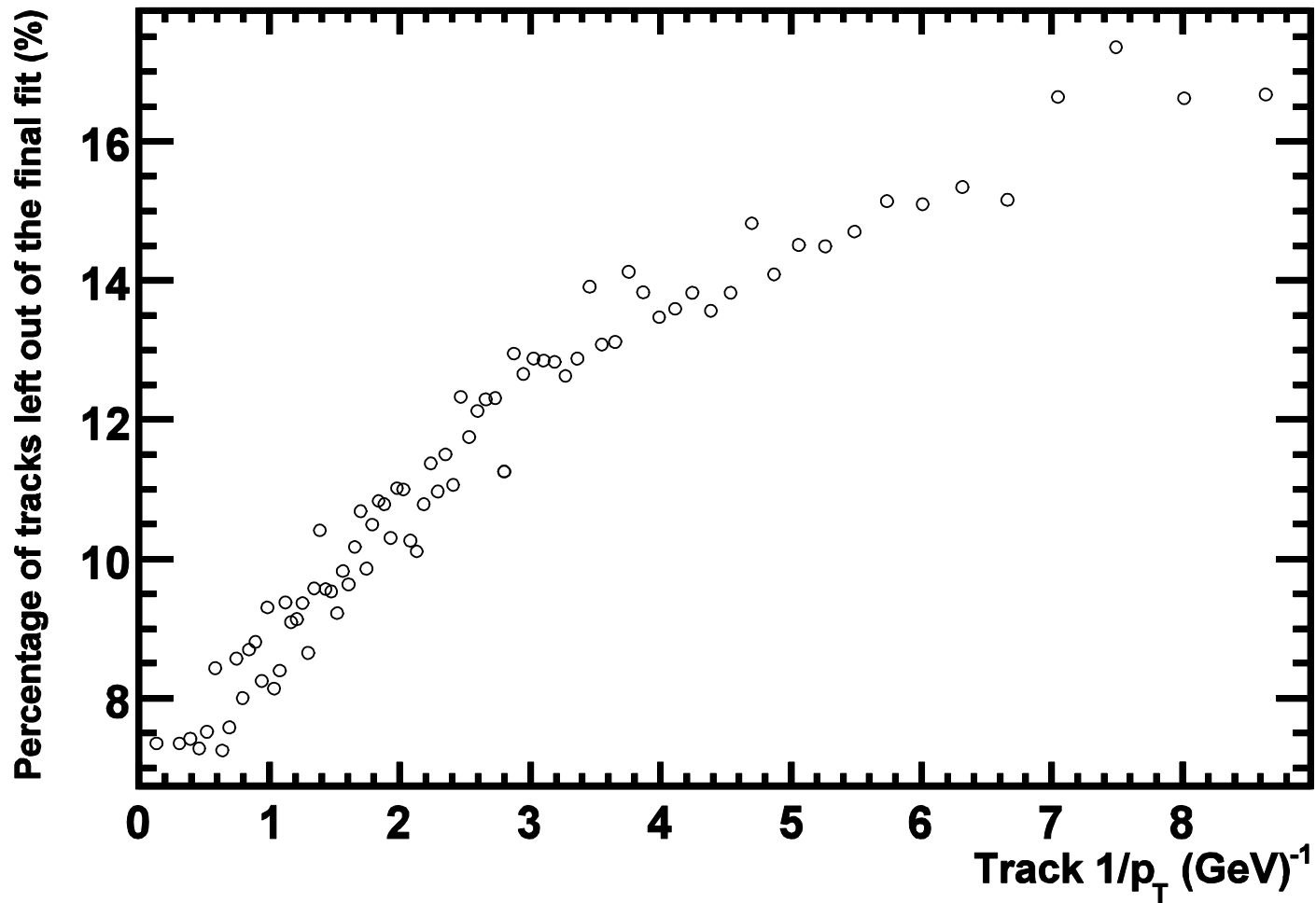


This plot shows the width of the pull in bins of  $p_T$ . The pull in any one bin is computed by dividing the measured  $\Delta_x$  for every track in that bin by the parameterized error. For perfect agreement the widths should be equal to 1.



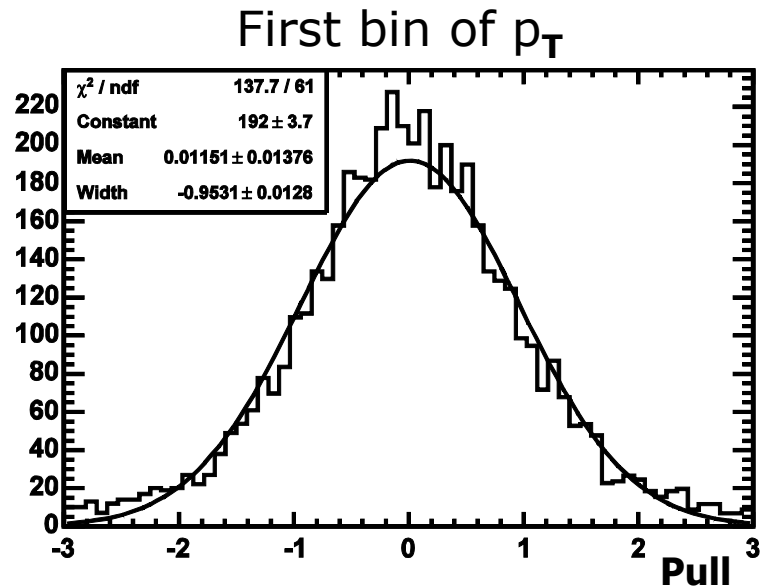
**HOW WELL IS THE ITERATIVE  
PROCEDURE ACTUALLY  
WORKING?**

# TRACKS OUT OF FIT

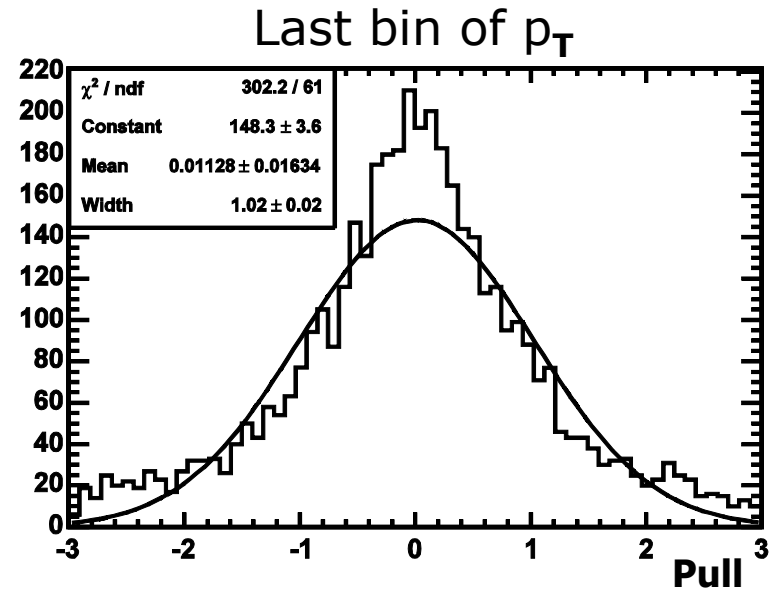
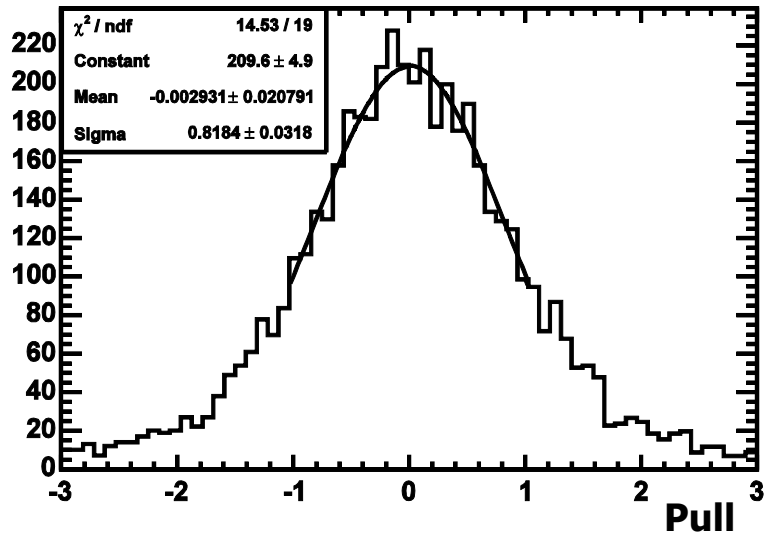


This plot shows the percentage of tracks removed by the iterative procedure before the final  $3\sigma$  fit

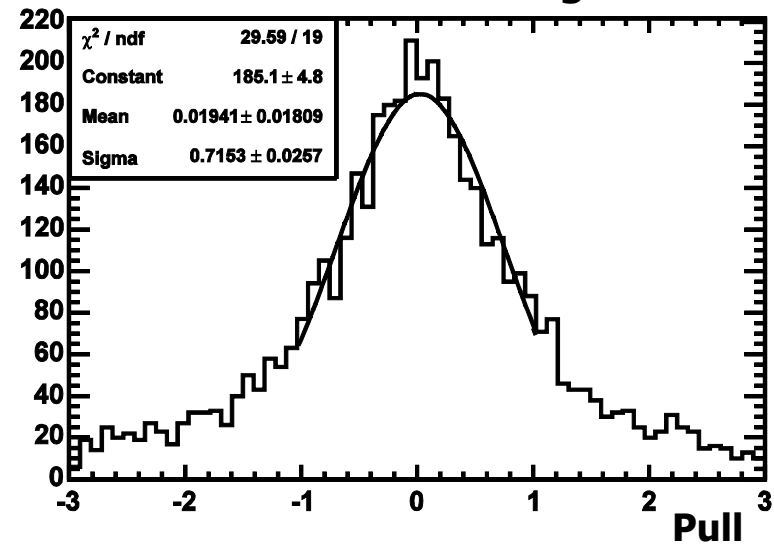
# FINAL $3\sigma$ GAUSSIAN FIT PULLS



Refitted in  $1\sigma$  region



Refitted in  $1\sigma$  region



## COMMENT ON ITERATIVE PROCEDURE

- Even after iteratively rejecting tracks, we do not get single gaussians, especially at low  $p_T$ .
- Are we overestimating the errors (maybe)? How do you quote a single width for something which is a double gaussian anyway?

## EFFECT OF NEW PARAM. ON HLT2 SEL.

Test the two parametrizations on a sample of  $B_s \rightarrow D_s K$  events, selected by requiring all final state particles to have a  $p_T > 600$  MeV

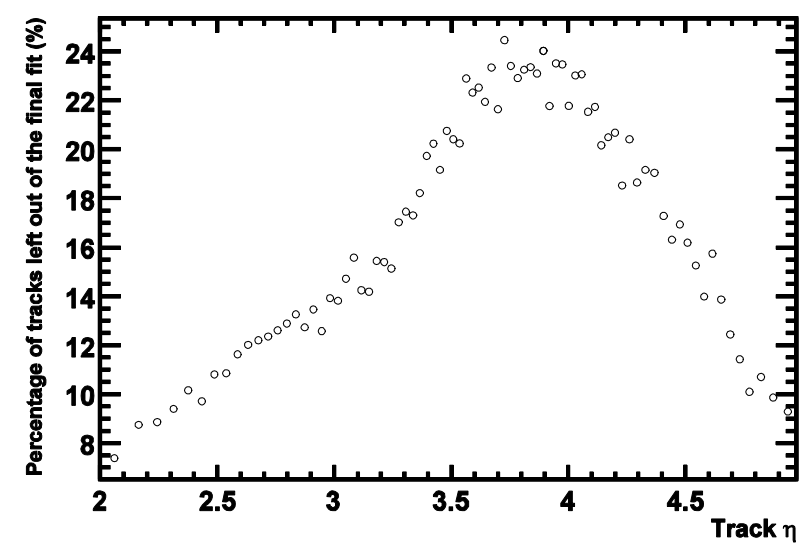
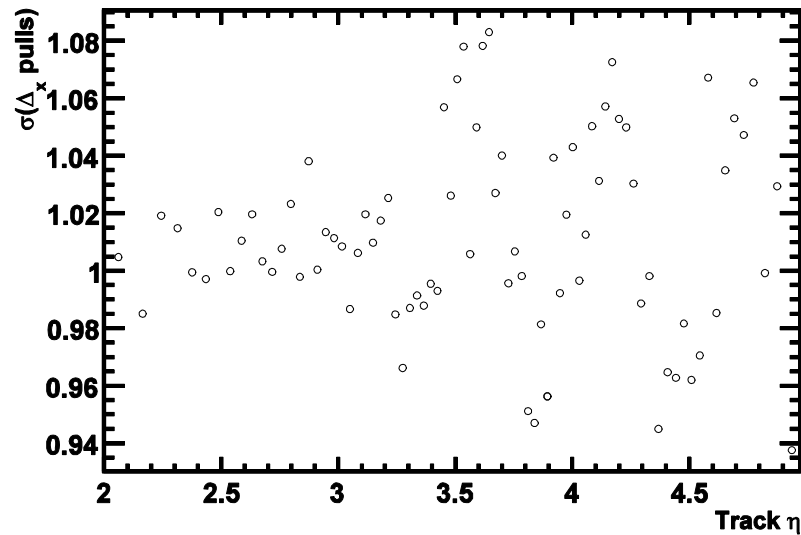
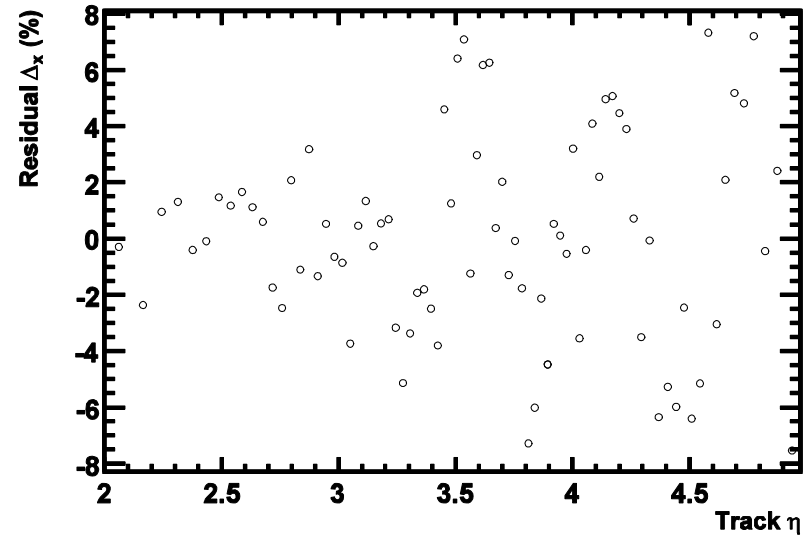
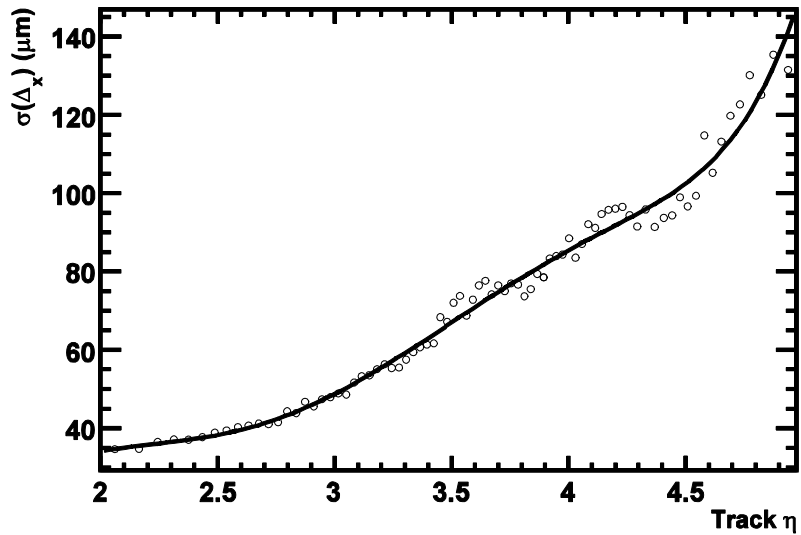
With DC06 Error parametrization	
Applied Cut	HLT2 Eff. wrt. Offline
IPS > 3 (all final state)	85%
B IPS < 4	98%
B flight significance > 8	80%

With DC04 Error parametrization	
Applied Cut	HLT2 Eff. wrt. Offline
IPS > 3 (all final state)	91%
B IPS < 4	100%
B flight significance > 8	87%

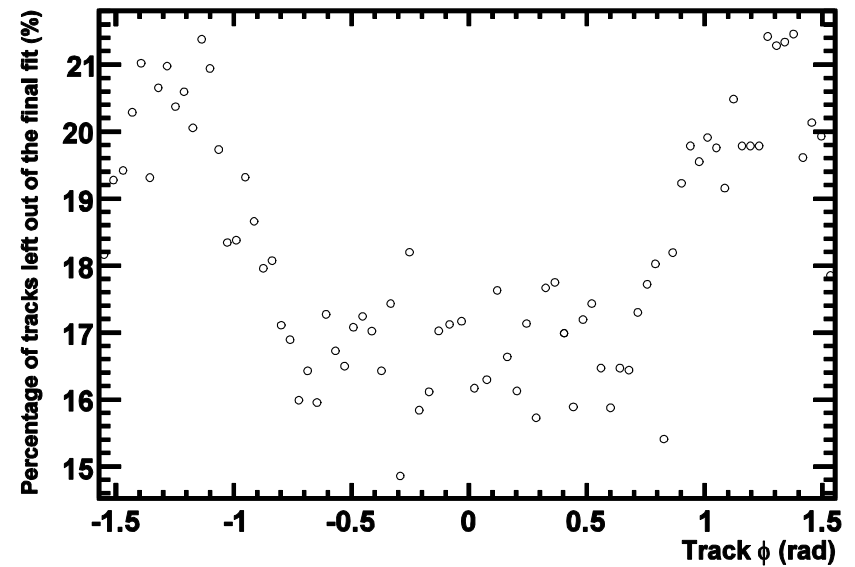
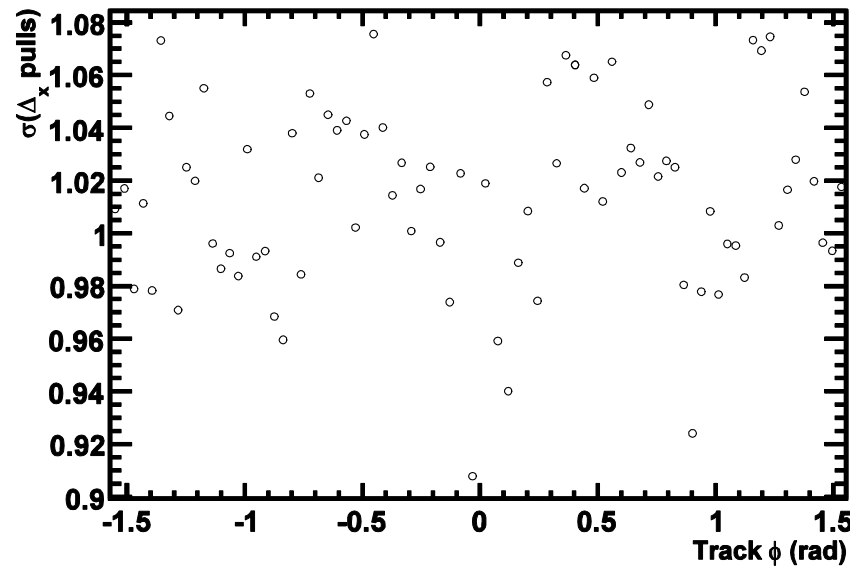
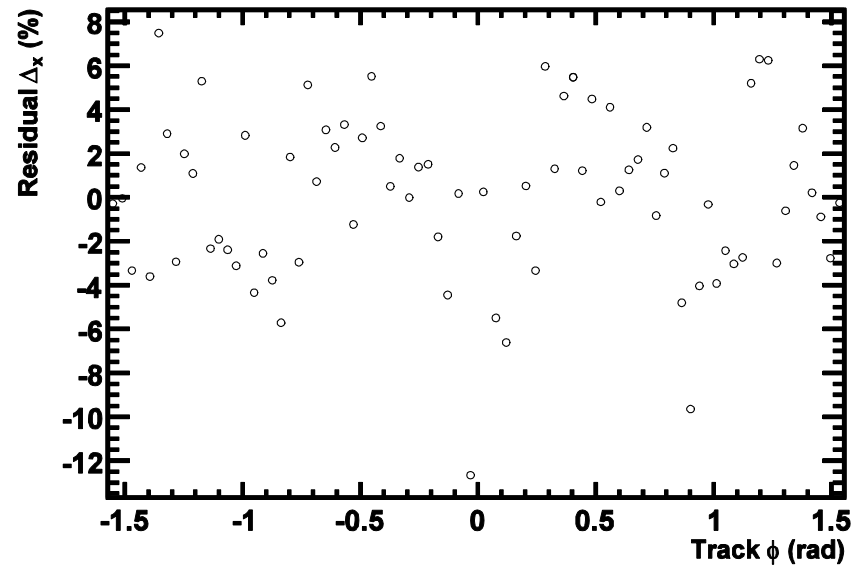
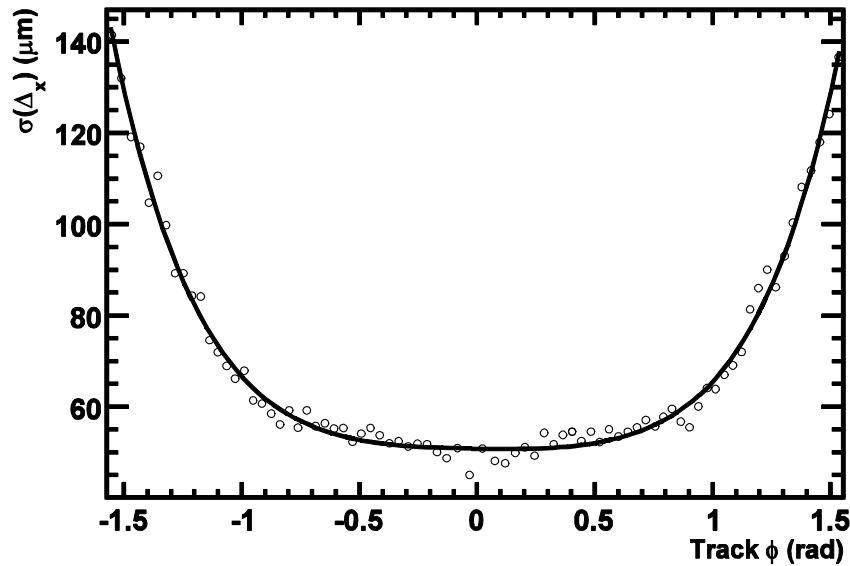
Unfortunately, the DC04 parametrization was underestimating the errors, so the relative efficiencies actually get worse, not better... on the other hand, the minbias rejection should get better as well.

# **DEPENDANCE ON OTHER VARIABLES**

# ERRORS AS A FUNCTION OF $\eta$



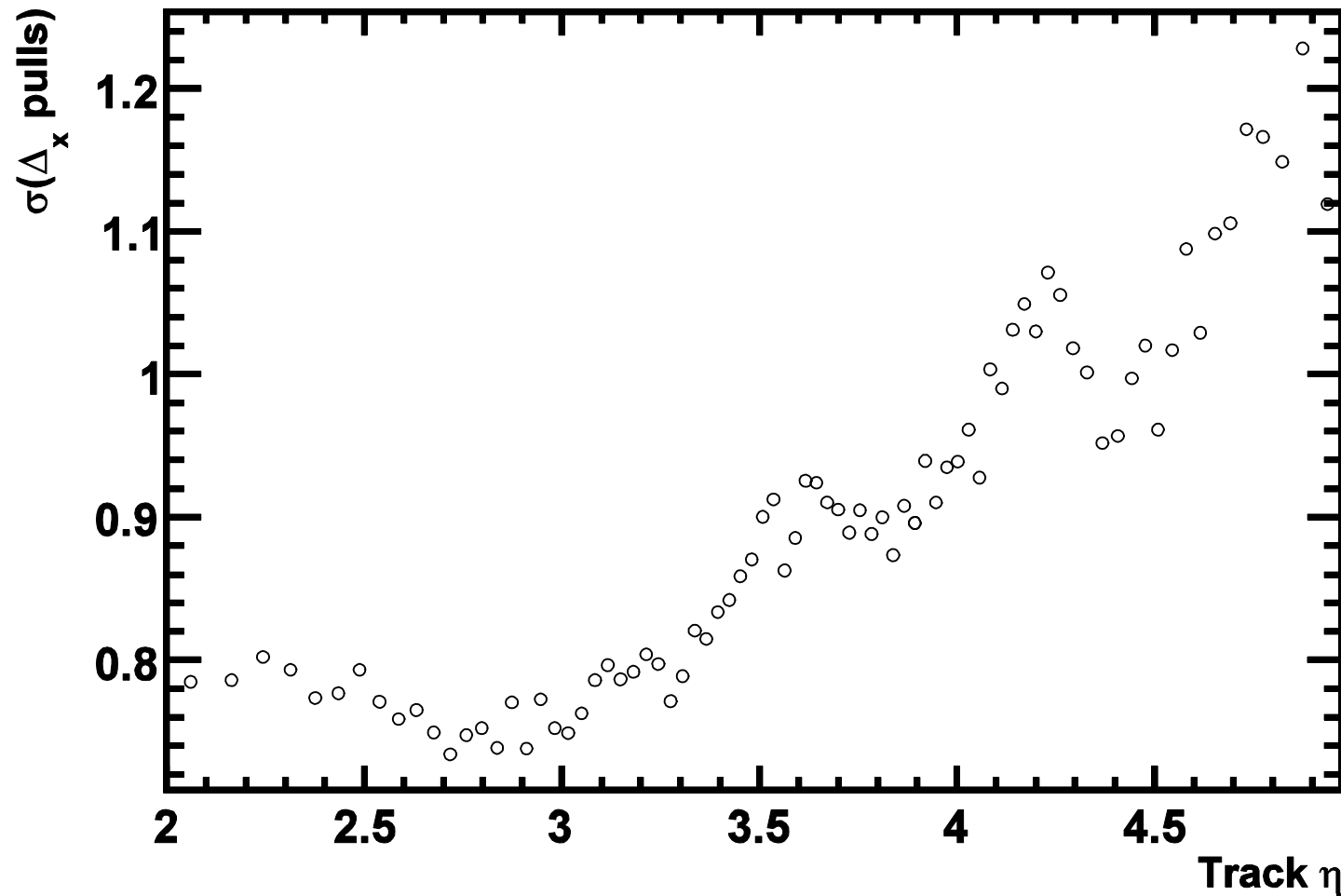
# ERRORS AS A FUNCTION OF $\phi$





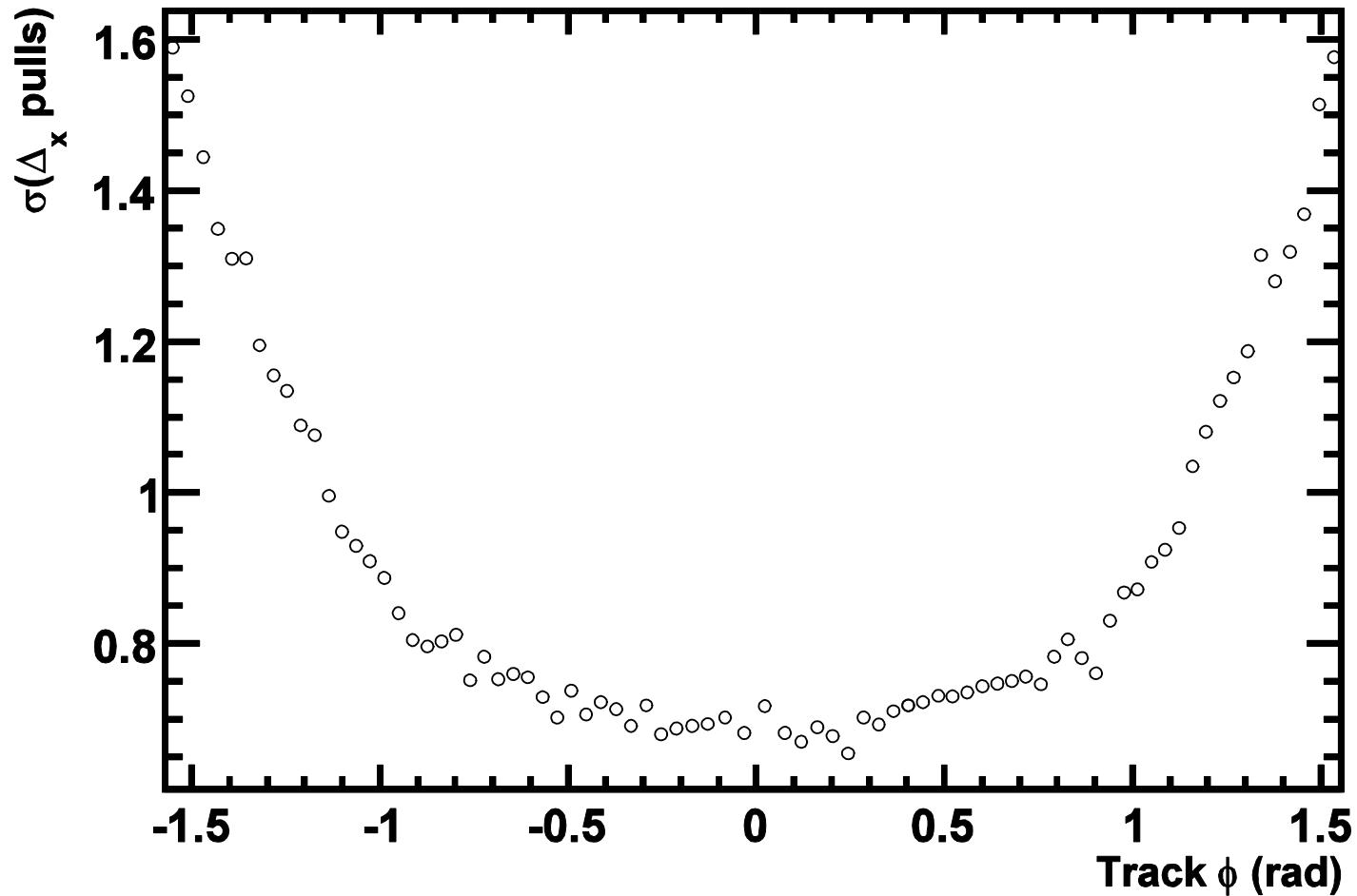
**RESIDUAL DEPENDENCIES  
WHEN FITTING AGAINST  $P_T$**

## RESIDUAL DEPENDENCY ON $\eta$



This plot shows the width of the pull in bins of  $\eta$  when the  $p_T$  parametrization is assumed. For perfect agreement the widths should be equal to one.

## RESIDUAL DEPENDENCY ON $\phi$



This plot shows the width of the pull in bins of  $\phi$  when the  $p_T$  parametrization is assumed. For perfect agreement the widths should be equal to one.

## TAKING RESIDUAL DEPENDENCIES INTO ACCOUNT

- As noted in the DC04 study, there are substantial correlations between the different residual correction
- Hence if we want an improvement on the  $p_T$  only correction, we would need a look-up table
- In first instance, consider the variables  $p_T$ ,  $\phi$ , and  $\eta$ ; each split into 80 bins
  - The table then has 512000 entries (half if you assume perfect symmetry in  $\phi$ )
  - Presents certain logistical difficulties... can it be implemented like magnetic field map?
  - Do we need it? Would need more than 20,000 tracks to do the fit for the table.

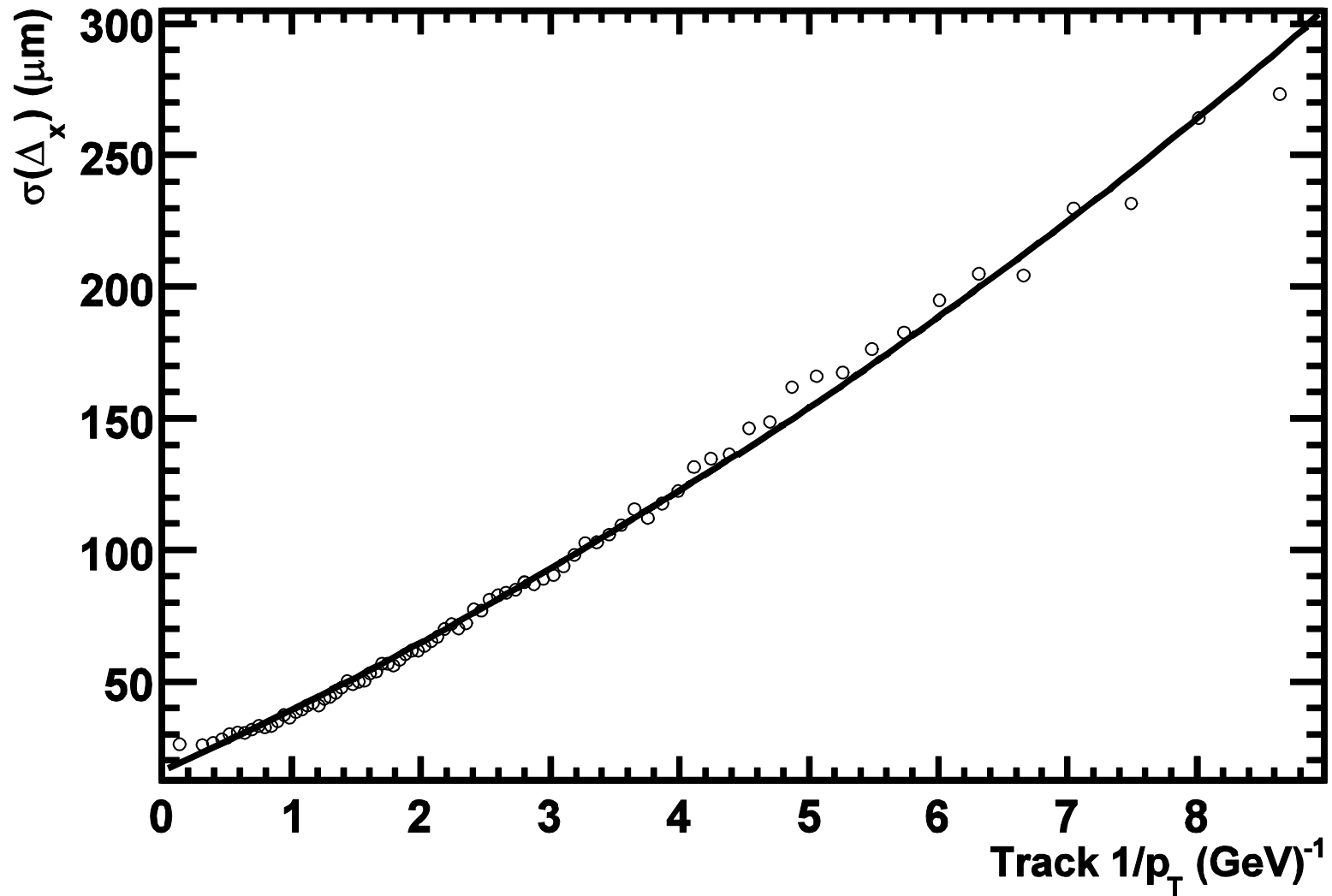
# **CONCLUSIONS AND FUTURE WORK**

## CONCLUSIONS AND FUTURE WORK

- The fitter is ready for release and public use
  - How do we envisage this to be used on real data? As a monitoring algorithm?
  - Do we want or need a look up table?
- Does the iterative procedure need refining?
  - Should switch to an unbinned fit for use with real data... sadly we now have a lot of time to work on this.
- Note detailing this work on the way soon

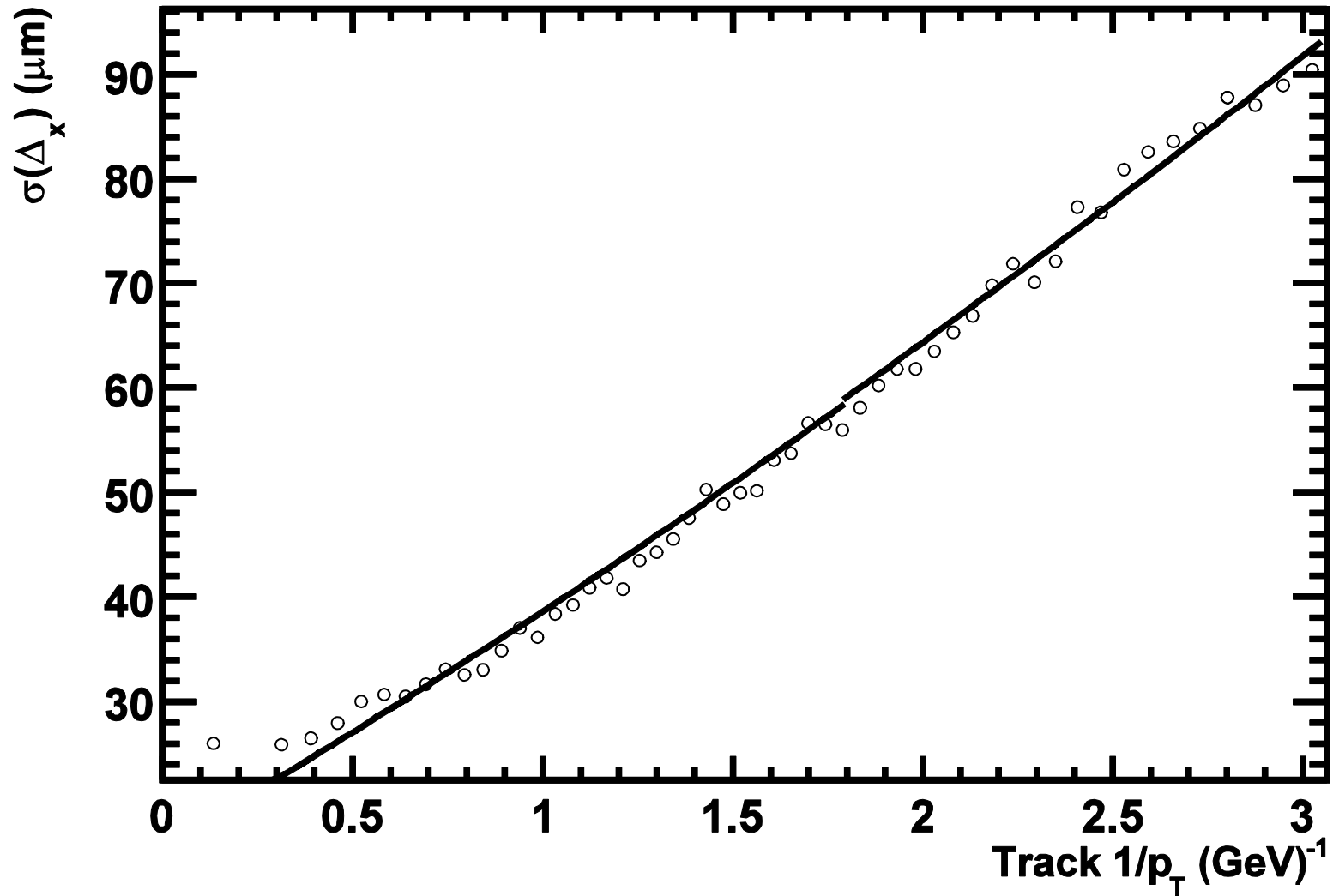
**BACKUP**

## FITTING WITH A QUADRATIC

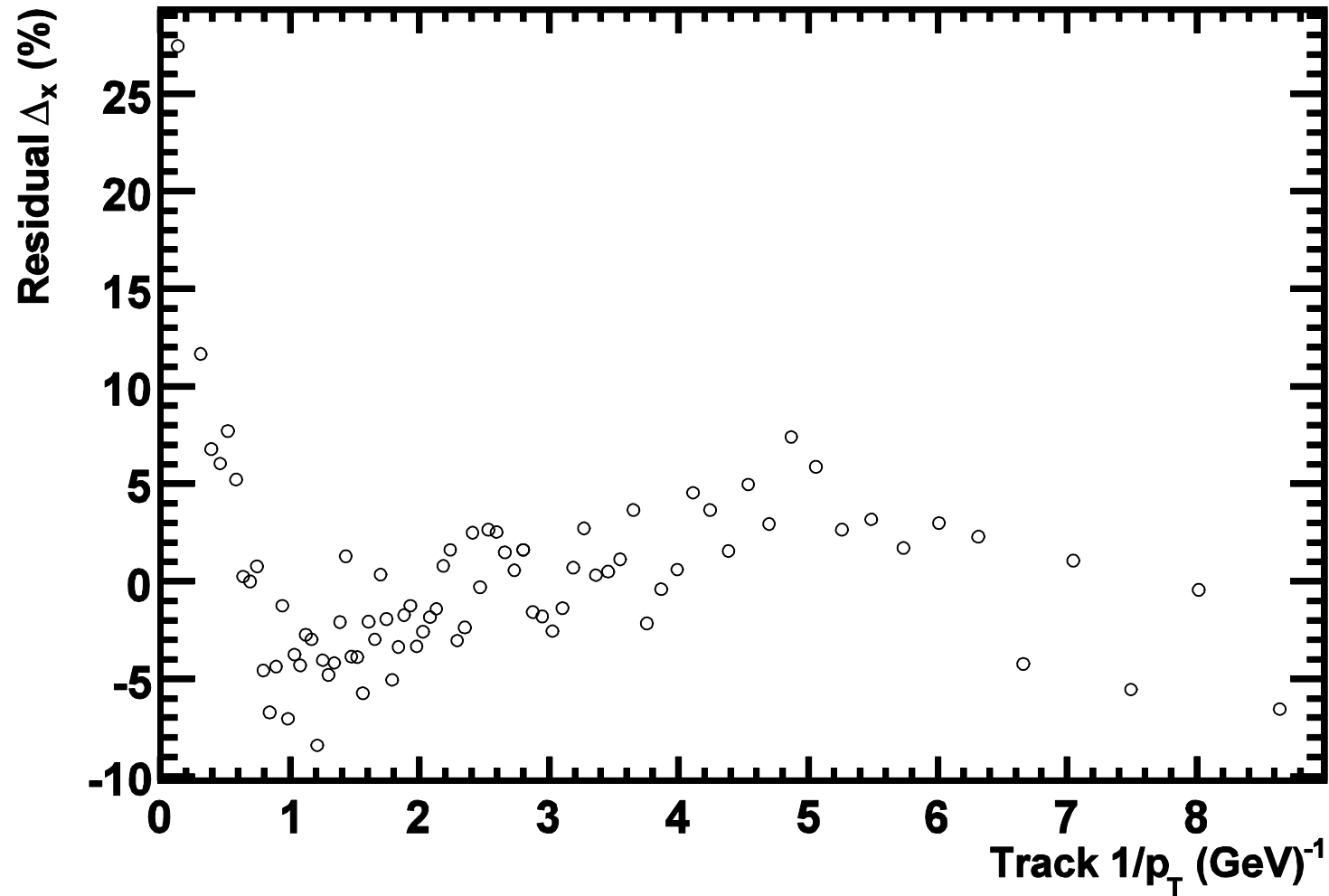




## FITTING WITH A QUADRATIC (ZOOM)

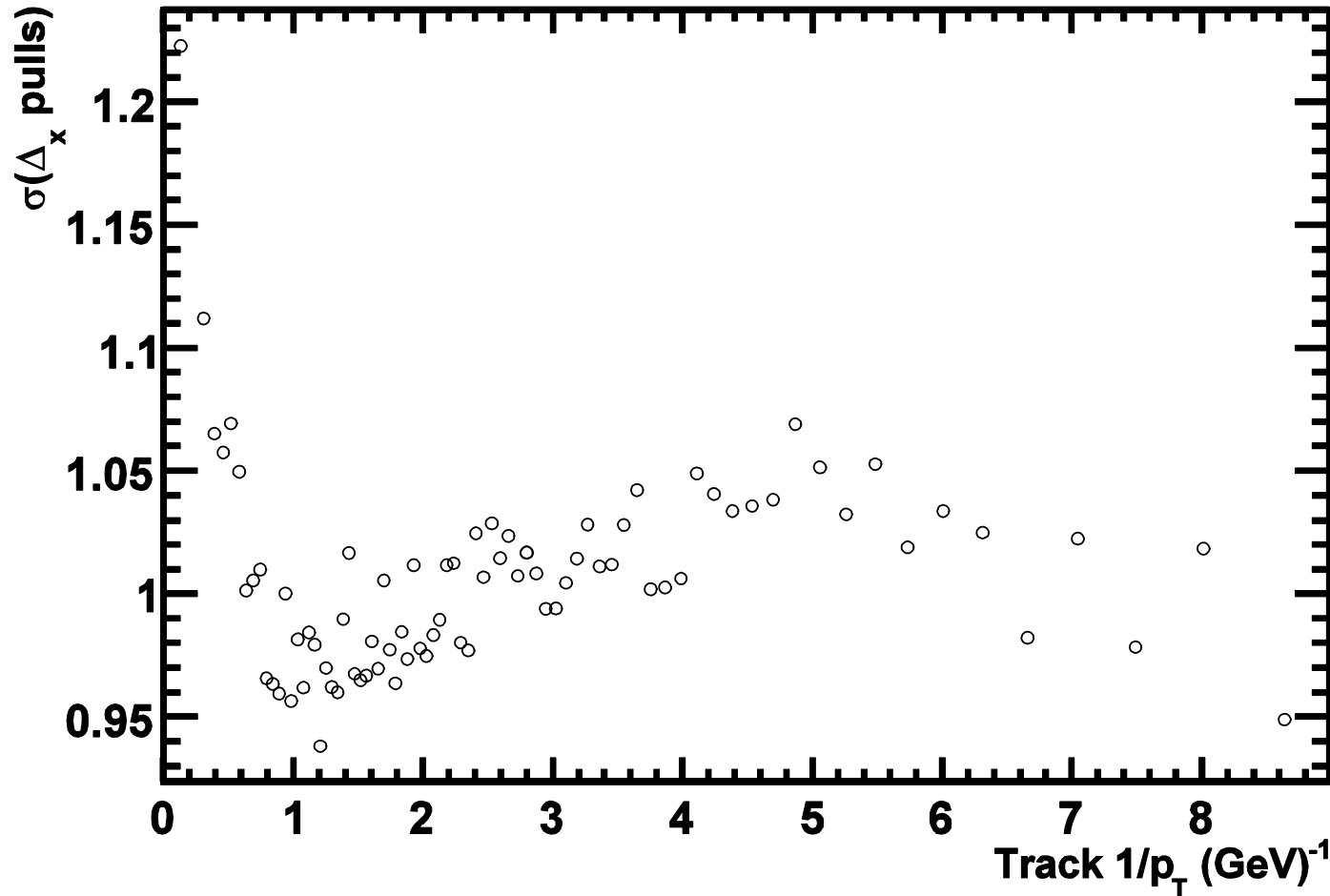


## RESIDUALS WITH QUADRATIC FIT



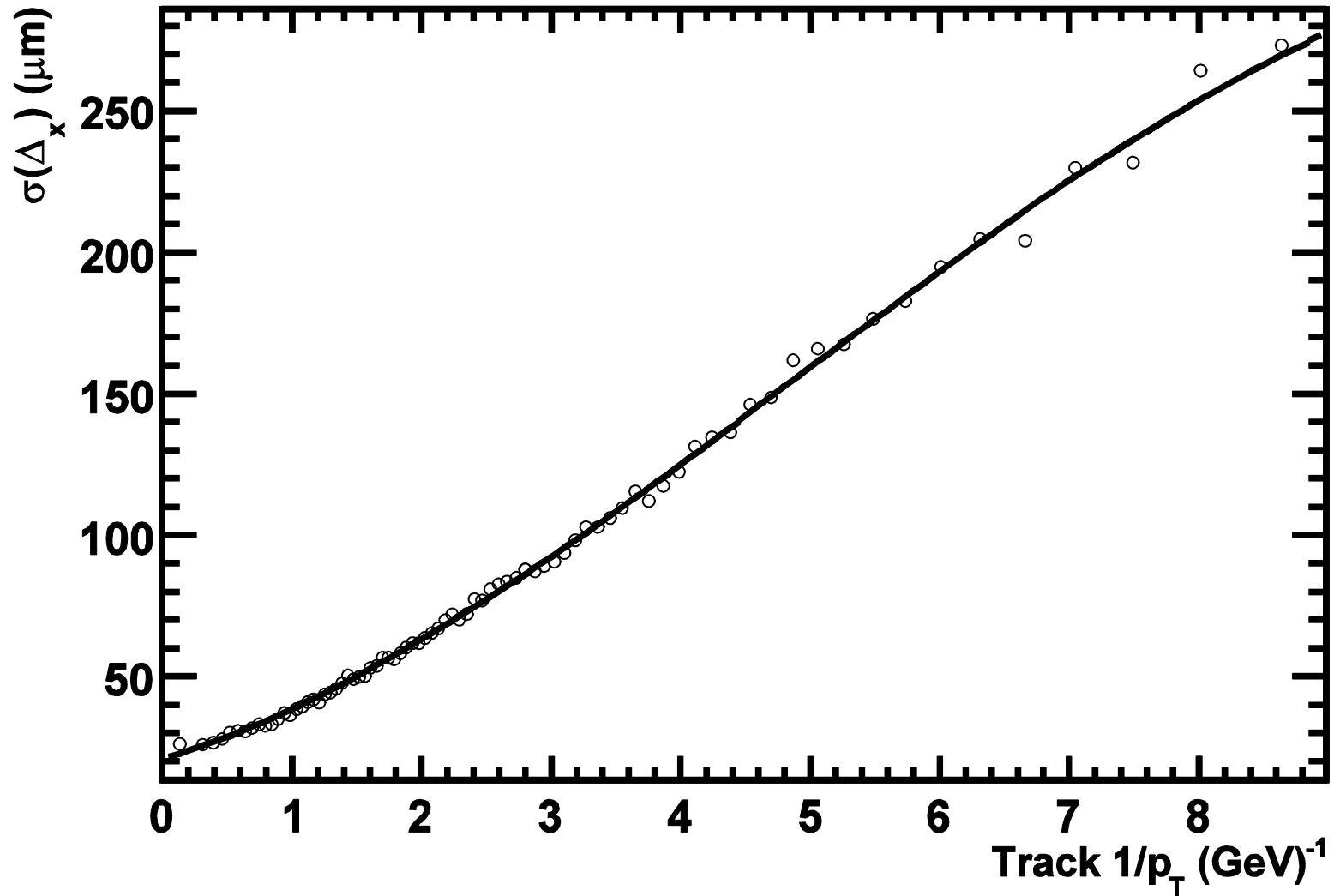
This plot shows the residual between the fitted and measured error for each bin of  $p_T$ , calculated at the midpoint of the bin.

## PULLS WITH QUADRATIC FIT

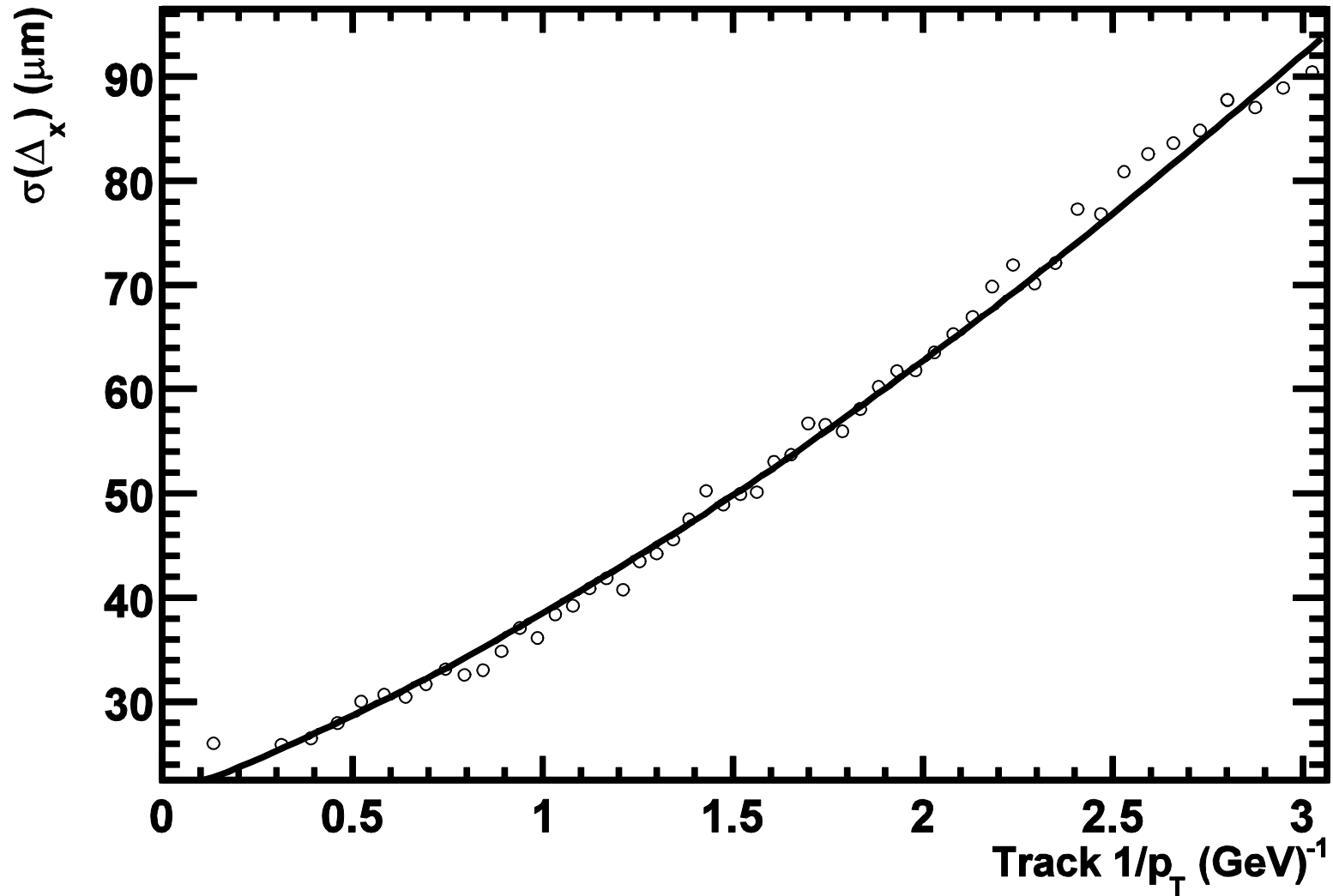


This plot shows the width of the pull in bins of  $p_T$ . The pull in any one bin is computed by dividing the measured  $\Delta_x$  for every track in that bin by the parameterized error. For perfect agreement the widths should be equal to 1.

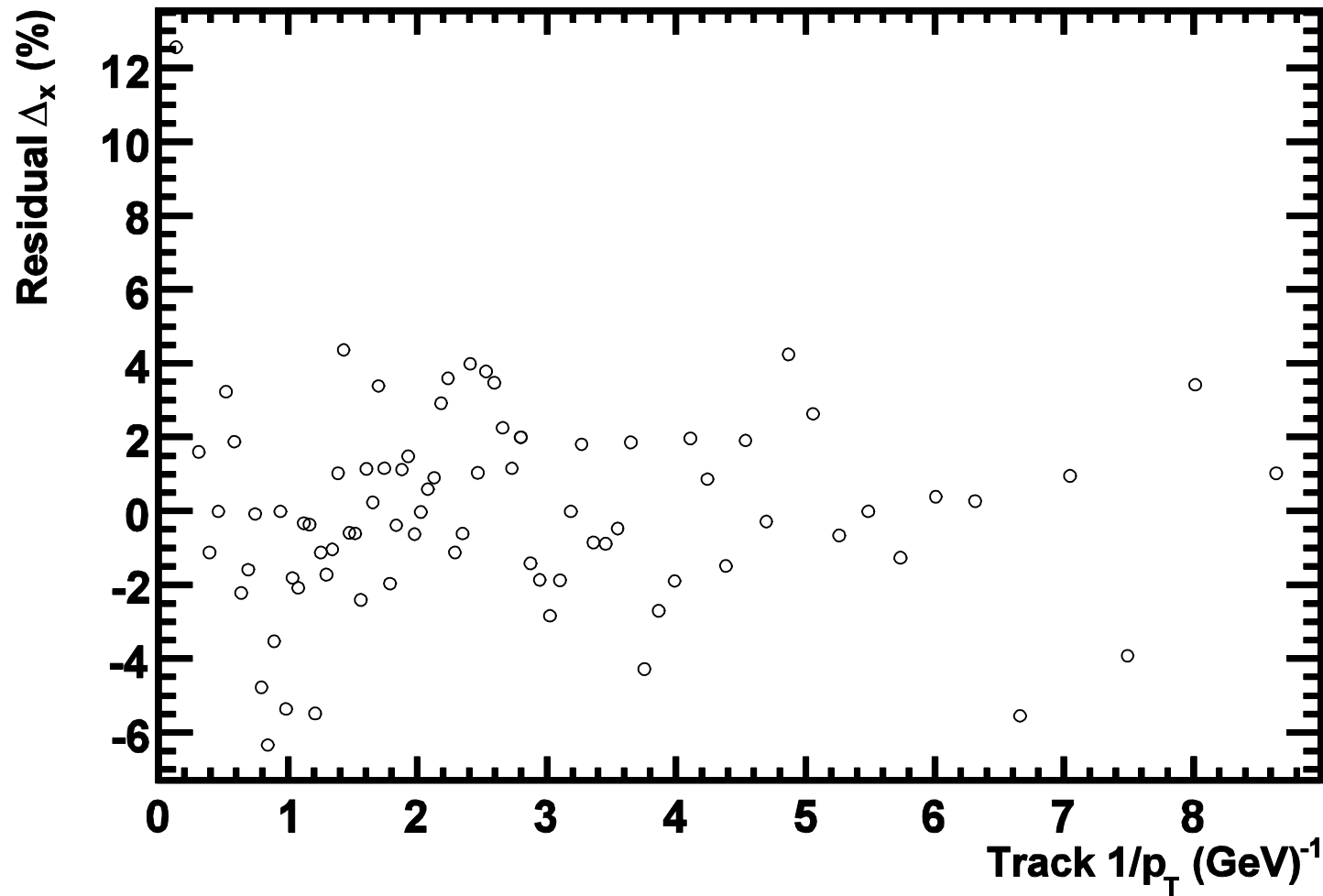
## FITTING WITH A CUBIC



## FITTING WITH A CUBIC (ZOOM)

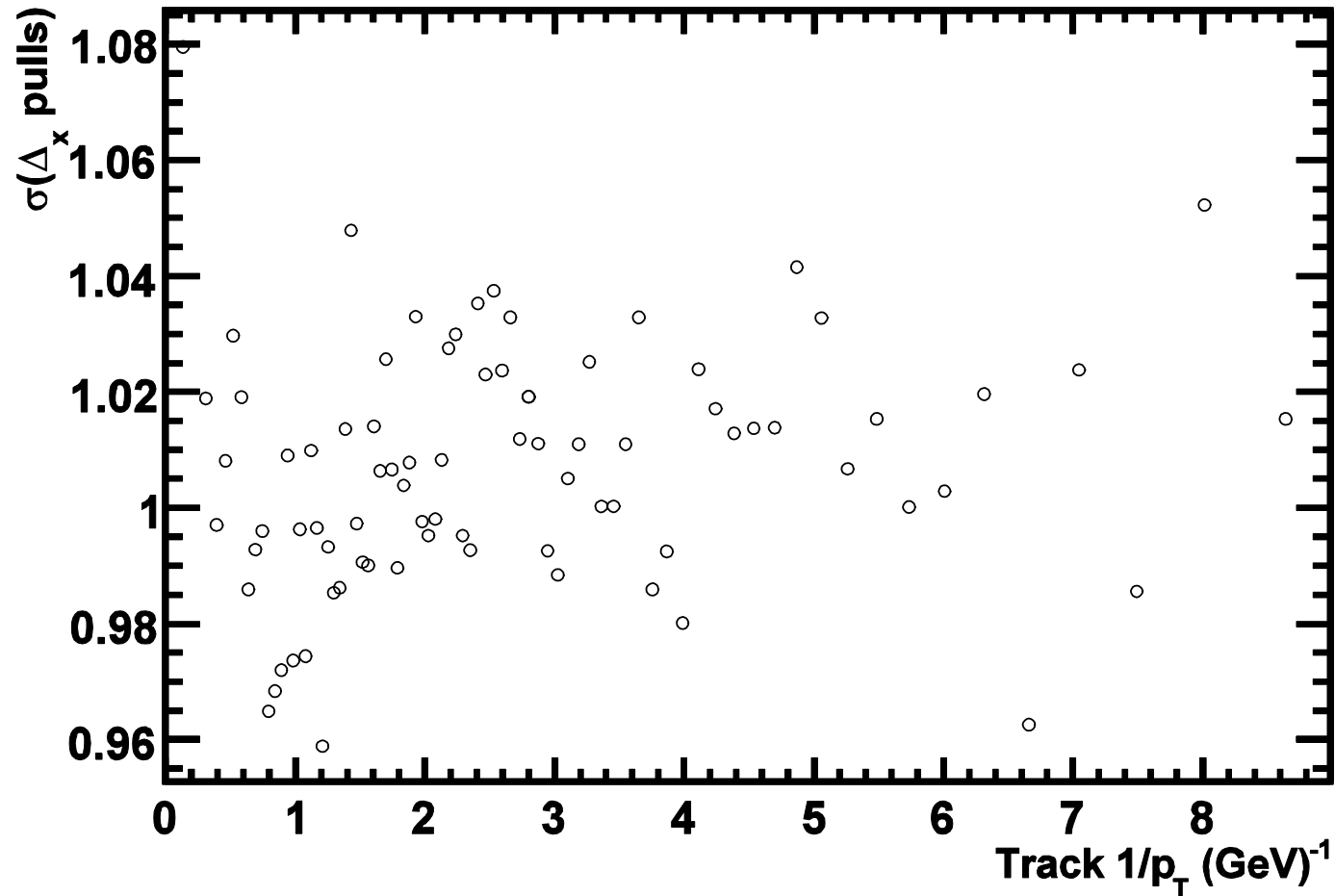


## RESIDUALS WITH CUBIC FIT



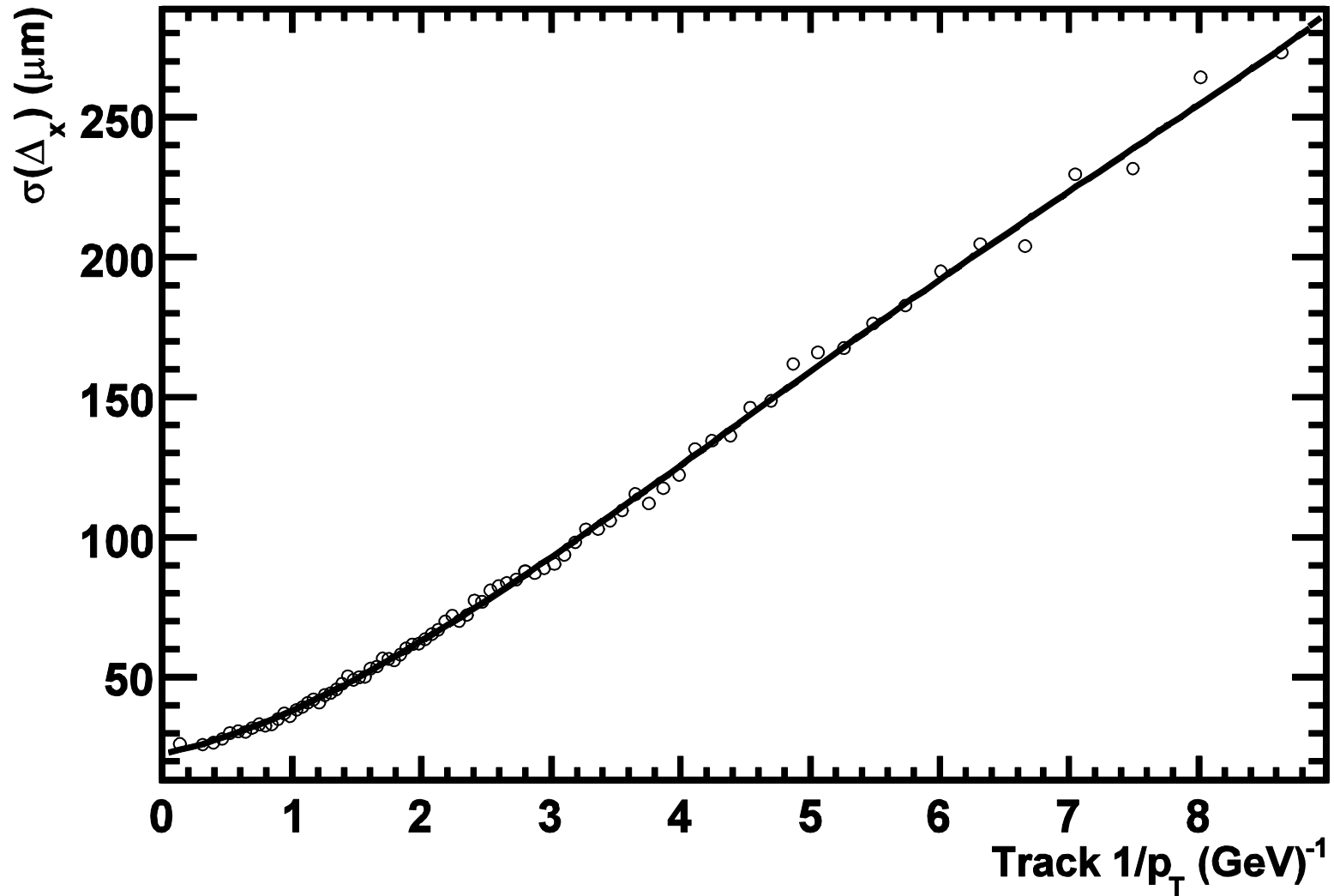
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## PULLS WITH CUBIC FIT



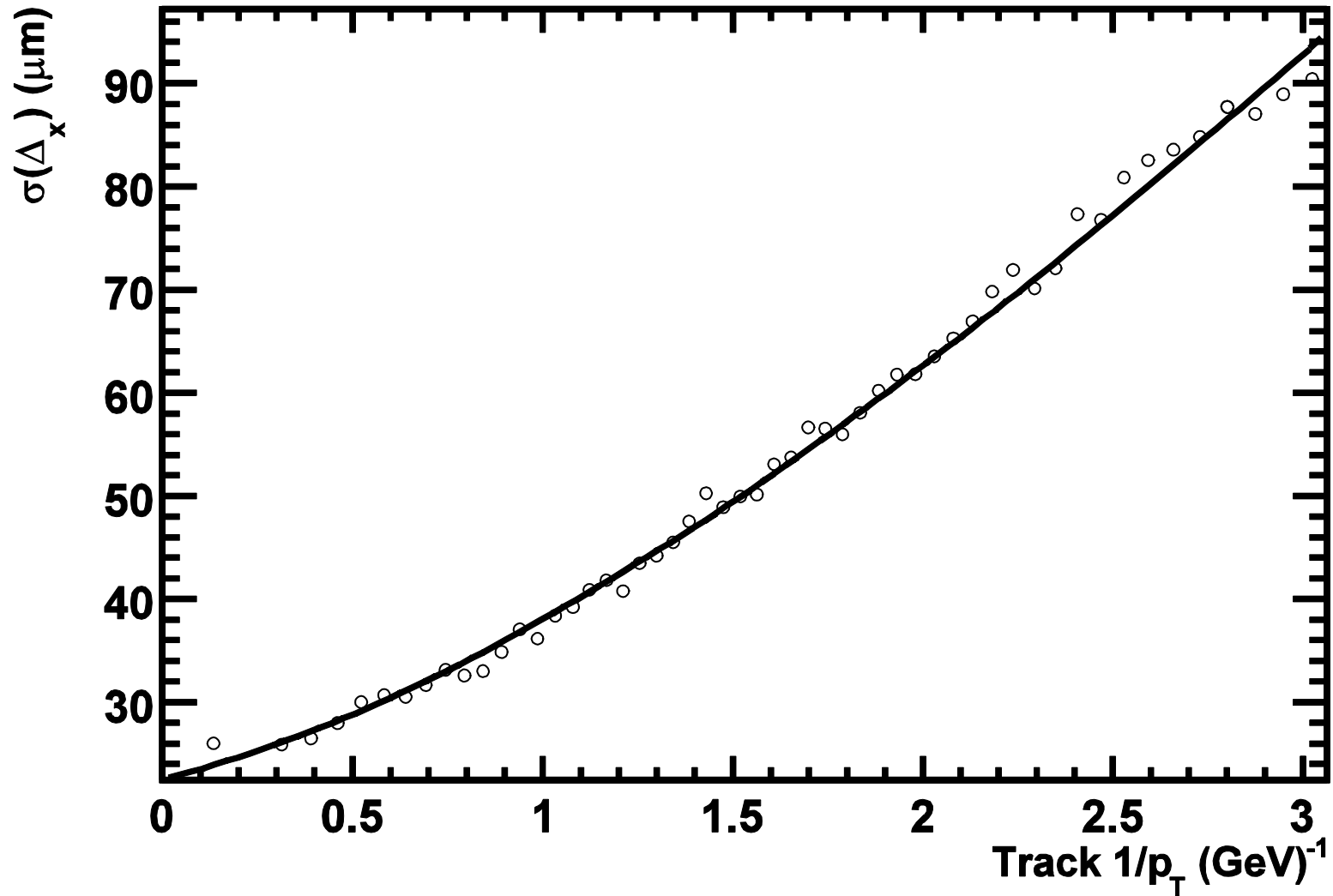
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## FITTING WITH A QUARTIC

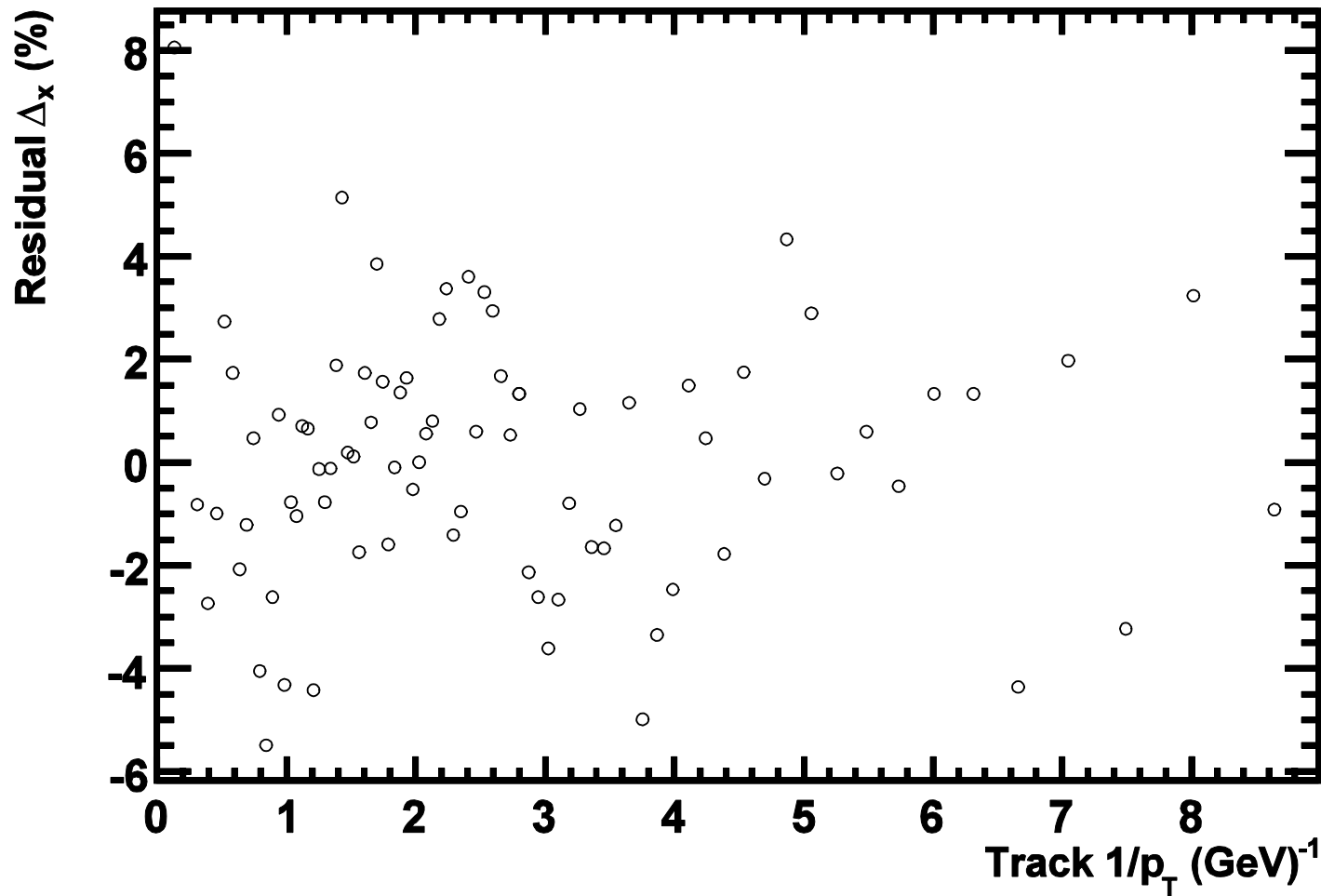




## FITTING WITH A QUARTIC (ZOOM)

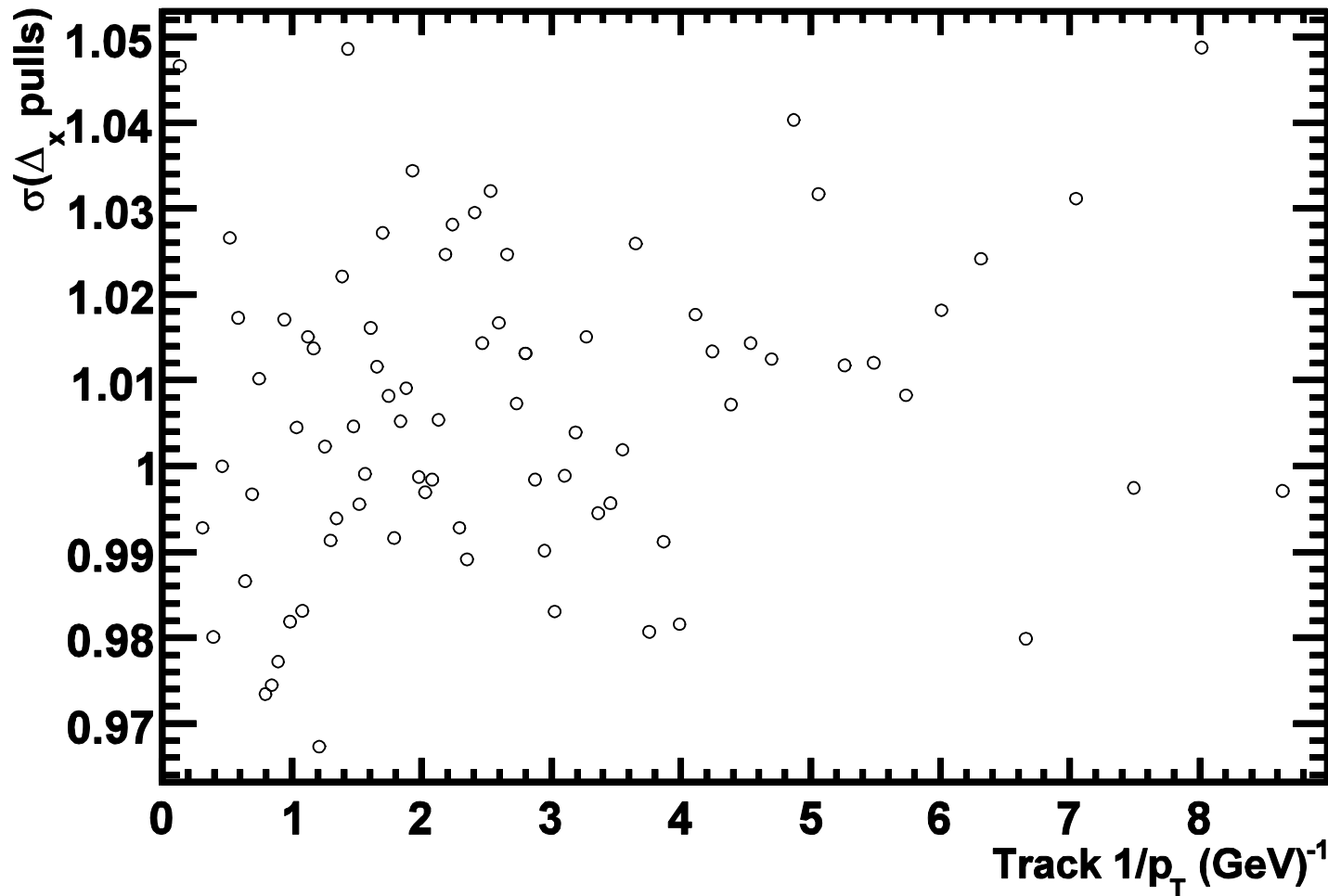


## RESIDUALS WITH QUARTIC FIT



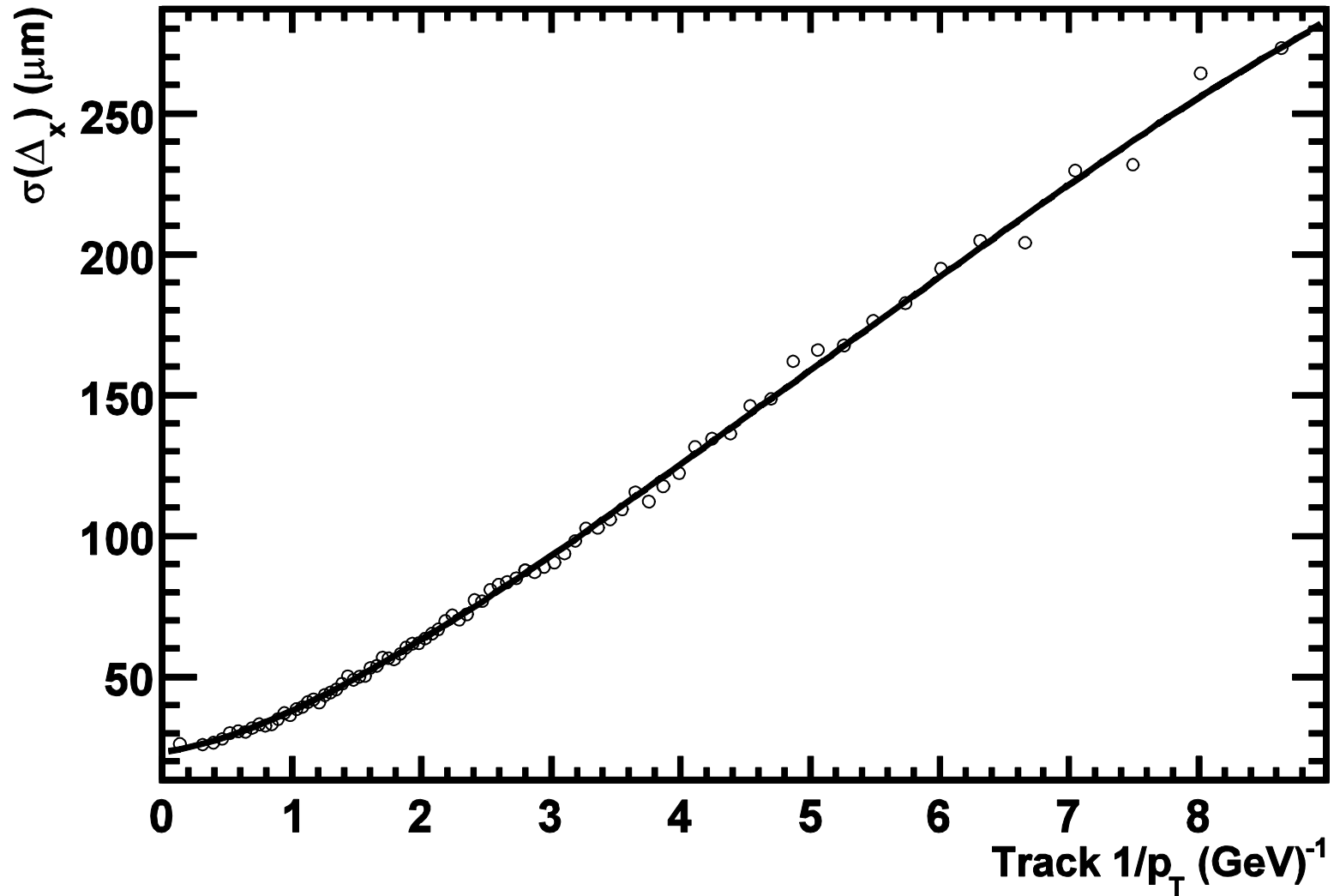
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## PULLS WITH QUARTIC FIT

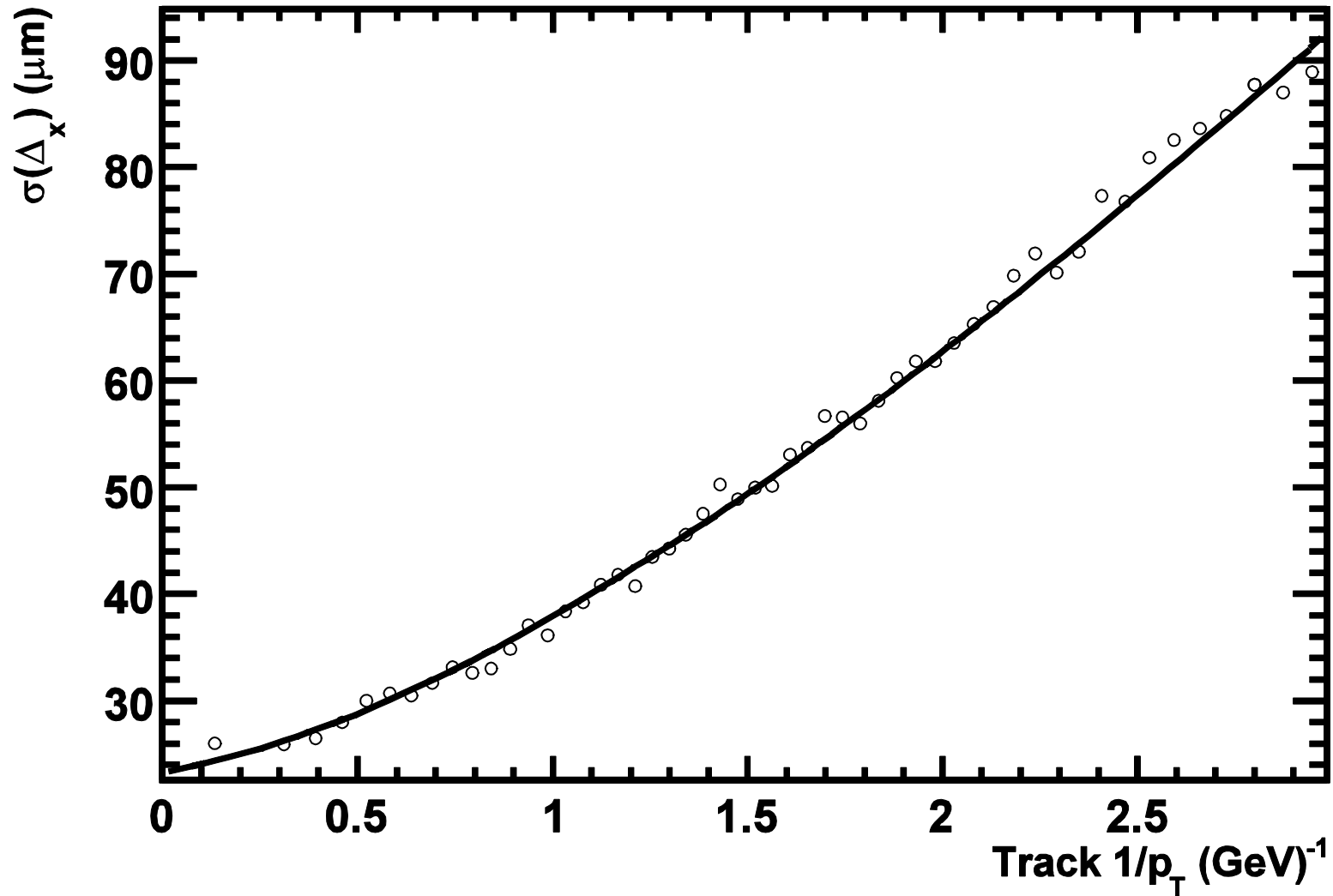


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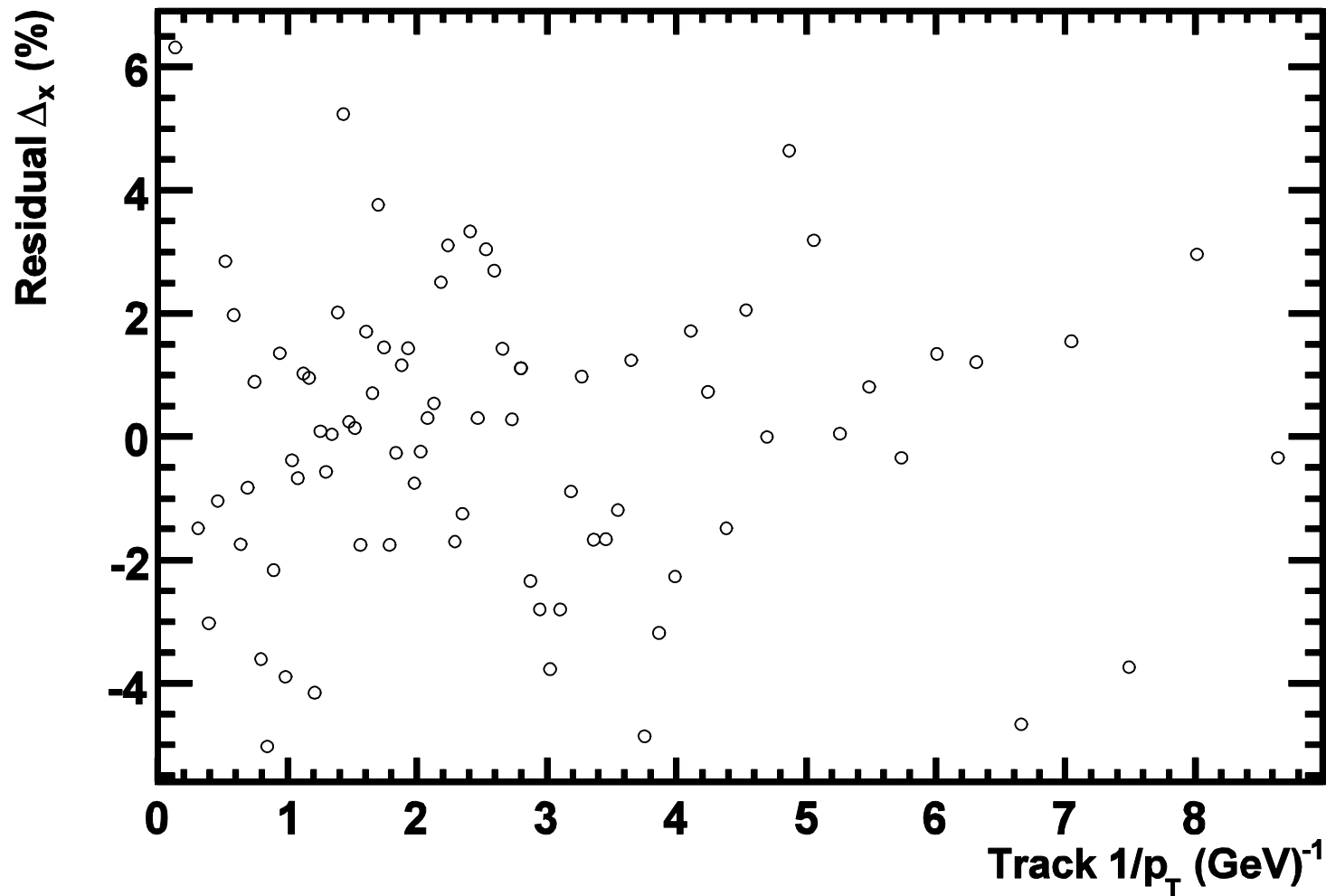
## FITTING WITH A QUINTIC



## FITTING WITH A QUINTIC (ZOOM)

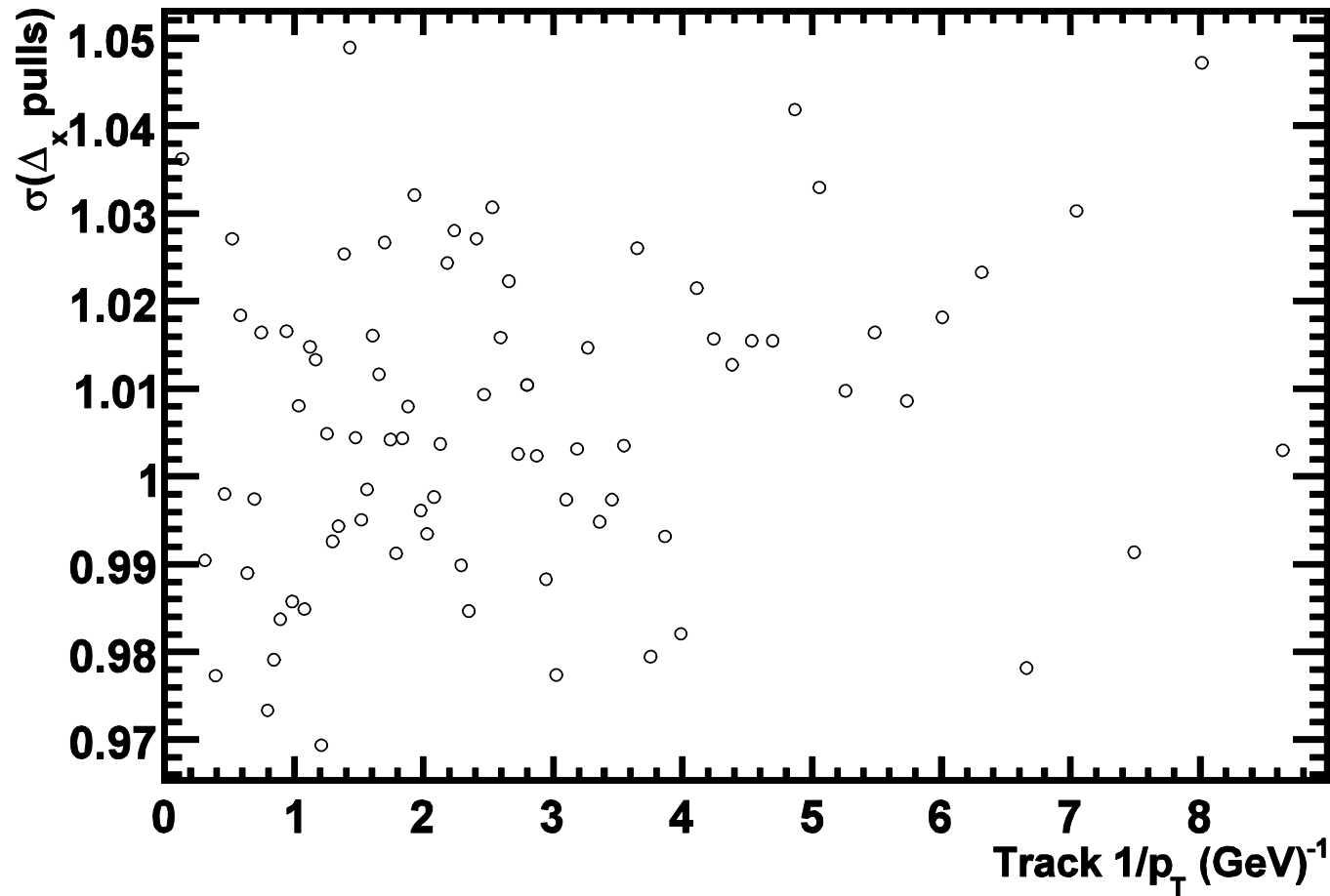


## RESIDUALS WITH QUINTIC FIT



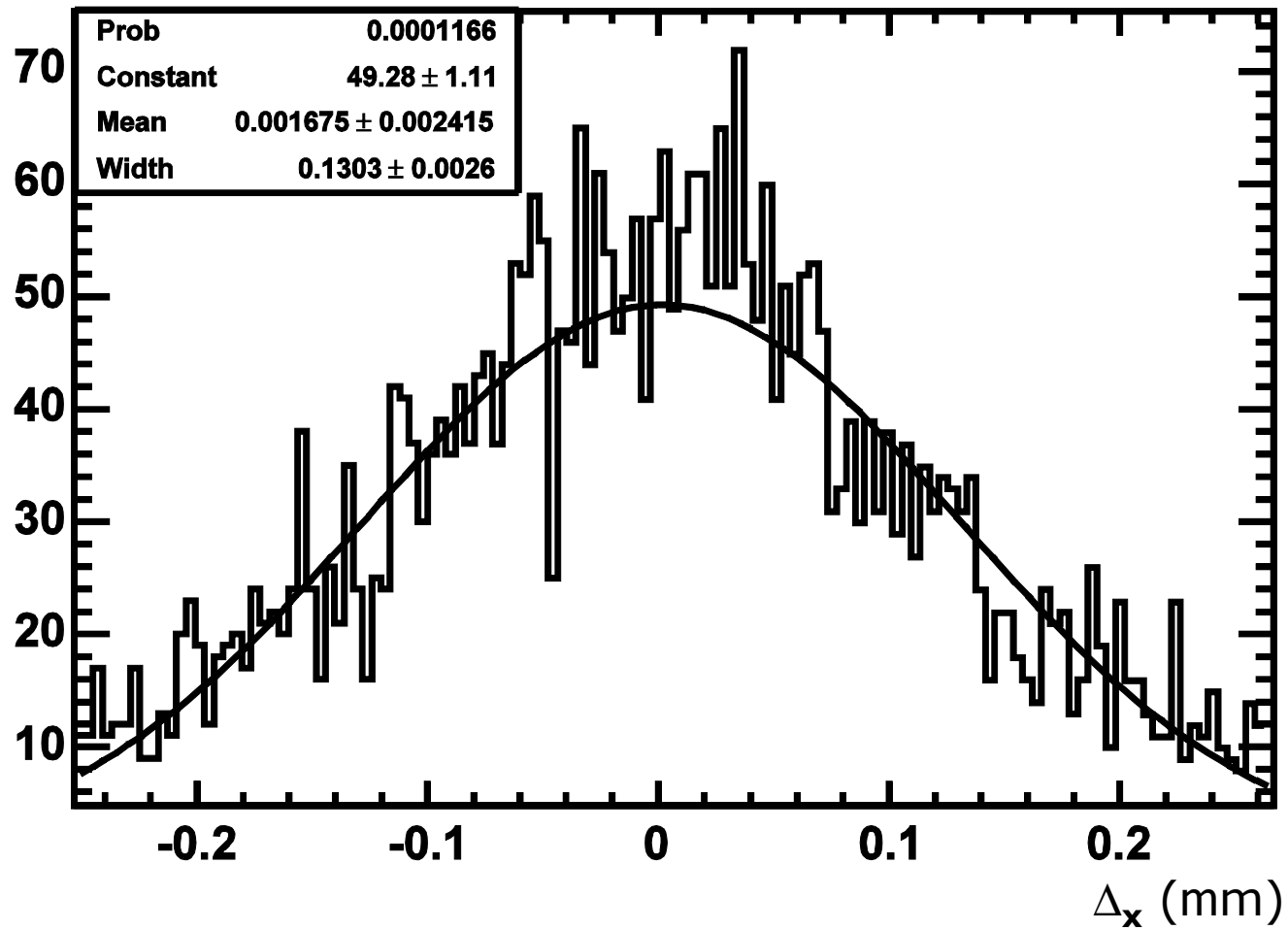
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## PULLS WITH QUINTIC FIT



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# INTERMEDIATE $1\sigma$ GAUSSIAN FIT





# DC04 RESULTS\*

\* Ref: Hugo Ruiz, LHCb 2005-012

# THE PARAMETRIZATION

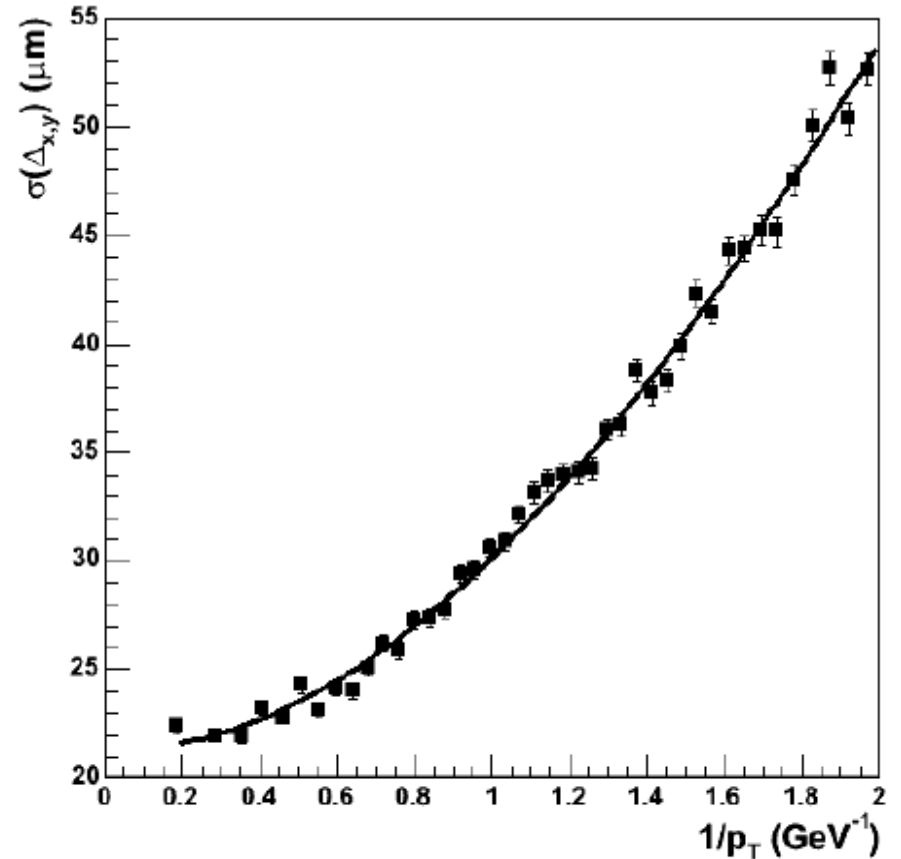
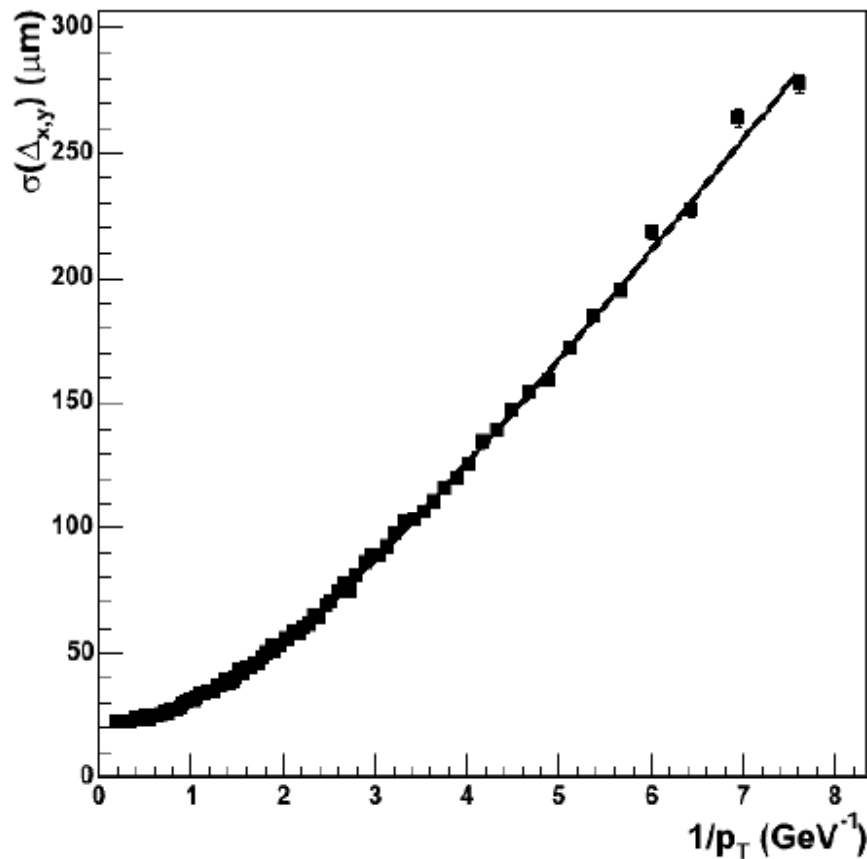


Figure 4: The best-fitting 4<sup>th</sup>-degree polynomial in two different ranges of  $1/p_T$ .

# RESIDUALS

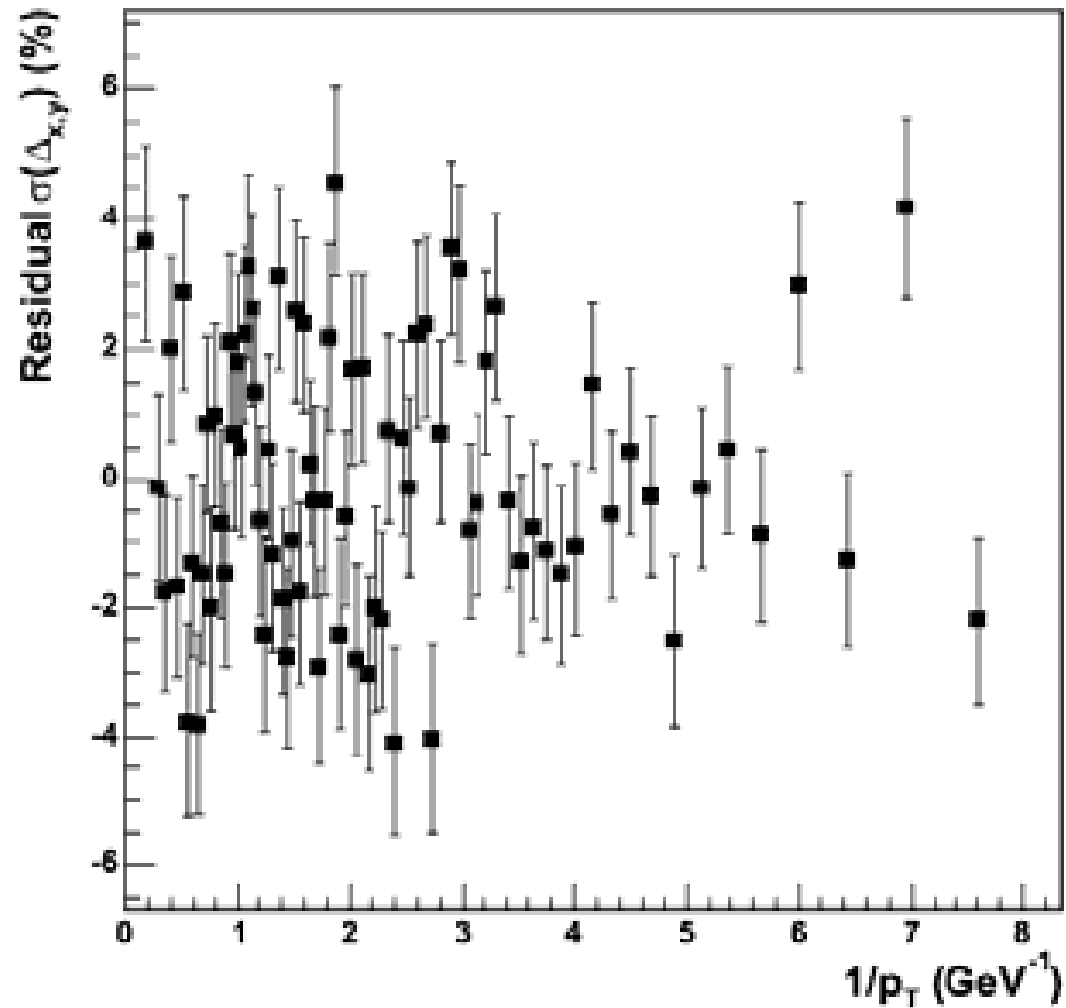


Figure 3: Residuals of the parameterization of the uncertainties

# TRACKS LEFT OUT OF THE FIT

- Because of the iterative procedure, some tracks are left out of the fit
  - The proportion varies with  $p_T$

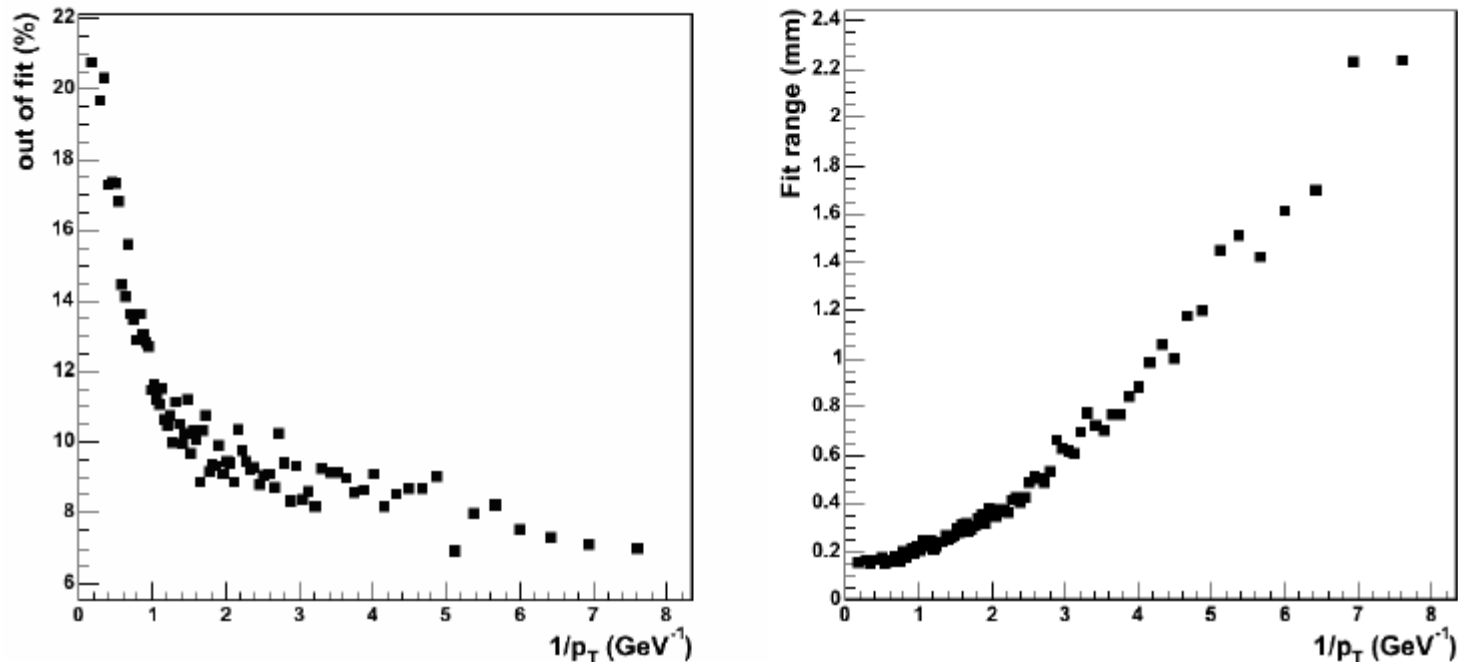


Figure 5: Left: fraction of tracks left out of the final fit due to the iterative process for fitting the  $\sigma$  in a  $\pm 3\sigma$  region. Right: size of the region where the final fit is performed.